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Fine-scale oceanographic drivers of reef manta ray (*Mobula alfredi*) visitation patterns at a feeding aggregation site

Running head:

Drivers of reef manta ray visitation patterns

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Abstract

Globally, reef manta rays (*Mobula alfredi*) are in decline and are particularly vulnerable to exploitation and disturbance at aggregation sites. Here, passive acoustic telemetry and a suite of advanced oceanographic technologies were used for the first time to investigate the fine-scale (5-min) influence of oceanographic drivers on the visitation patterns of 19 tagged *M. alfredi* to a feeding aggregation site at Egmont Atoll in the Chagos Archipelago. Boosted regression trees indicate that tag detection probability increased with the intrusion of cold-water bores propagating up the atoll slope through the narrow lagoon inlet during flood tide, potentially transporting zooplankton from the thermocline. Tag detection probability also increased with warmer near-surface temperature close to low tide, with near-surface currents flowing offshore, and with high levels of backscatter (a proxy of zooplankton biomass). These combinations of processes support the proposition that zooplankton carried from the thermocline into the lagoon during the flood may be pumped back out through the narrow inlet during an ebb tide. These conditions provide temporally limited feeding opportunities for *M. alfredi*, which are tied on the tides. Results also provide some evidence of the presence of Langmuir Circulation, which transports and concentrates zooplankton, and may partly explain why *M. alfredi* occasionally remained at the feeding location for longer than that two hours. Identification of these correlations provides unique insight into the dynamic synthesis of fine-scale oceanographic processes which are likely to influence the foraging ecology of *M. alfredi* at Egmont Atoll, and elsewhere throughout their range.

Keywords: Acoustic telemetry, boosted regression trees, foraging ecology, internal waves, cold-water bores, Langmuir Circulation.

44 Introduction

45 Reef manta rays (*Mobula alfredi*) are large zooplanktivorous elasmobranchs of the
46 family Mobulidae (Hosegood *et al.*, 2020; Marshall *et al.*, 2009; White *et al.*, 2017). The
47 global population is widely distributed in highly fragmented subpopulations throughout
48 tropical and sub-tropical waters of the Indo-West Pacific Oceans (Couturier *et al.*, 2012;
49 Marshall *et al.*, 2019). Subpopulations appear to have limited home ranges, typically centred
50 around coral reef ecosystems (McCauley *et al.*, 2014; Kessel *et al.*, 2017; Couturier *et al.*, 2018;
51 Setyawan *et al.*, 2018). Aggregation behaviour is characteristic of the species, whereby
52 subpopulations will concentrate the majority of their activities at certain ‘hotspot’ locations
53 (Couturier *et al.*, 2018; Setyawan *et al.*, 2018; Harris *et al.*, 2020). These aggregations
54 typically occur within particular discrete habitats (Stevens, 2016; Harris *et al.*, 2020) such as
55 cleaning stations (O’Shea *et al.*, 2010), and locations where they engaged in social (Stevens,
56 2016; Perryman *et al.*, 2019) or reproductive activities (Stevens *et al.*, 2018). Large feeding
57 aggregations also occur, and are often associated with the species’ reliance on dense
58 assemblages of prey (Armstrong *et al.*, 2016) in a largely oligotrophic environment (Morel *et*
59 *al.*, 2010).

60 Extensive targeted and bycatch fisheries of *M. alfredi*, driven in part for their gill
61 plates [pre-branchial appendages, used to filter their zooplankton prey from the water (Paig-
62 Tran *et al.*, 2013), which are utilised in the Asian medicinal trade (O’Malley *et al.*, 2017)], has
63 led to dramatic subpopulation declines in recent decades (Couturier *et al.*, 2013; Lawson *et*
64 *al.*, 2017; Rohner *et al.*, 2017; Marshall *et al.*, 2019). Population recovery from such
65 exploitation is hindered by their conservative life-history traits; the species are slow-growing,

late to mature and only have a few offspring in their lifetime (Dulvy *et al.*, 2014; Stevens, 2016).

Mobula alfredi are particularly vulnerable to exploitation and changes in climate at feeding aggregation sites. For example, anthropogenic disturbance may reduce individual *M. alfredi* fitness by driving them away from productive feeding areas (Venables *et al.*, 2016; Murray *et al.*, 2019), which has been highlighted as a major conservation concern for the species (Murray *et al.*, 2019; Harris *et al.*, 2020). Feeding behaviour may also be disrupted by enhanced stratification driven by rising sea surface temperatures, which can decrease marine phytoplankton (Roxy *et al.*, 2016), and with it zooplankton biomass (Richardson, 2008).

Studies which investigate *M. alfredi* aggregation behaviour have associated their occurrence with various broadscale physical factors, such as wind speed, moon phase, sea surface temperature, and tidal phase (Dewar *et al.*, 2008; Jaine *et al.*, 2012; Couturier *et al.*, 2018; Peel *et al.*, 2019b). However, the fine-scale changes in the oceanographic environment that potentially drive feeding aggregations have yet to be investigated.

Situated in the central Indian Ocean, the Chagos Archipelago (Figure 1) has been uninhabited for many decades (excluding Diego Garcia Atoll) (Sheppard *et al.*, 2012). Due to the lack of human influence, such as coastal development and anthropogenic pollution, the region is considered virtually pristine (Readman *et al.*, 2013). Owing to the region's unique marine environment, a no-take marine protected area (MPA), which encompasses the entire exclusive economic zone (EEZ) (640,000km²) except for a 3nm exclusion around the boundary of Diego Garcia Atoll, was established in 2010 (Sheppard *et al.*, 2012). The archipelago supports a subpopulation of *M. alfredi* which is largely undocumented due to the remoteness of the location and strict protective measures; as is the region's physical oceanographic

environment (Hosegood *et al.*, 2019). Broadscale studies conducted in the region indicated that Egmont Atoll, situated in the southwest of the archipelago, provides key habitats for this *M. alfredi* subpopulation (Harris, 2019; Andrzejaczek *et al.*, 2020). Feeding *M. alfredi* are regularly observed around the atoll (Harris, 2019); behaviour which is thought to be associated with shallow bathymetry, low current speeds, and cooler sea surface temperatures (Jaine *et al.*, 2012; Armstrong *et al.*, 2016; Couturier *et al.*, 2018; Harris, 2019; Peel *et al.*, 2019b). Together, these factors may act to induce upwelling of nutrients, increasing primary and secondary production (McManus *et al.*, 2005). Furthermore, currents interacting with topography may aggregate zooplankton (Genin *et al.*, 2005), resulting in highly productive feeding grounds for a range of species, including *M. alfredi* (Hosegood *et al.*, 2019).

Field observations have identified an *M. alfredi* feeding aggregation ‘hotspot’ at the north of Egmont Atoll (Harris and Stevens, unpublished data). However, *M. alfredi* feeding activity can be dramatically different from one day to another, with little apparent change in broadscale oceanographic conditions (Harris, 2019). Therefore, a greater understanding of how *M. alfredi* respond to fine-scale environmental drivers is needed. Here, passive acoustic telemetry and *in situ* oceanographic monitoring is used to investigate *M. alfredi* activity at Egmont Atoll, and assess what physical factors drive fine-scale (5-min) visitation patterns at the observed feeding aggregation hotspot. This study aims to enhance the current understanding of *M. alfredi* foraging ecology by providing detailed insight into their fine-scale movement patterns in response to natural changes in their oceanographic environment.

Methods

Study site

The Chagos Archipelago is comprised of seven atolls, several large submerged banks and more than 60 low lying islands, located at the southernmost end of the Lakshadweep–Maldives–Chagos ridge; 450km south of the Maldives (Sheppard *et al.*, 2012) (Figure 1). Egmont Atoll’s geomorphology is typical of an atoll with an interior lagoon system which is separated from the open ocean by reef crests and flats, with narrow connecting channel systems (Woodroffe and Biribo, 2011). During six expeditions, between January 2015 and December 2019 (Harris and Stevens, unpublished data), the authors repeatedly observed aggregations of *M. alfredi* engaged in feeding activity at a site called Manta Alley (Figure 1). At this foraging hotspot, using in-water observations (Figure 2) and ROVs, *M. alfredi* were recorded feeding at the surface and down to a depth of 120 m (Harris and Stevens, unpublished data; Diaz and Foster, unpublished data). Manta Alley is located 100 m north of Egmont Atoll’s northeast rim, where two narrow (<350 m) passages are situated. From the shallow lagoon passages (<5 m), the topography slopes steeply down (up to 47°) before reaching a 50 m wide plateau 80 m from the lagoon, with a depth of 65–71 m. On the seaward side, there is a narrow ridge which inclines steeply (up to 39°) to a height of approximately 10 m, followed by another sharp slope down to >100m (Robinson and Hosegood *et al.*, unpublished data) (Figure 1).

Oceanographic Moorings

Two instrumented oceanographic moorings were deployed in Manta Alley (Figure 1) from a research ship on 30th December 2019. Both moorings were positioned within Manta Alley. The first was a subsurface taut-line mooring deployed in 66 m, with the uppermost buoyancy element at a depth of 20 m. Temperature was measured by RBRSolo³T temperature sensors positioned at 2 m intervals from 4 m to 48 m above the seabed. In addition to the

temperature sensors, RBR Concerto conductivity-temperature-depth (CTD) sensors with a sampling interval of 5s were positioned at 2 m and 50 m above the bed. An acoustic receiver (see *acoustic receiver array* section below) was positioned approximately 7 m below the near-surface CTD, at 43 m above the bed. The second mooring, deployed 182 m southeast of the first, comprised an upward-facing Nortek Signature 500kHz acoustic Doppler current profiler (ADCP), mounted on a subsurface buoy 3 m above the seabed. Both moorings were recovered on 17th March 2020; however, the Nortek Signature 500kHz ADCP had ceased sampling on 10th March 2020.

Acoustic tag deployment

Tagging activities were carried out at Egmont Atoll between 19th November 2019 - 3rd December 2019 while freediving. Twenty VEMCO V16-4x acoustic transmitter tags (Vemco Inc., Nova Scotia, Canada), each tethered to a titanium anchor (Wildlife Computers) with a small diameter cable, were deployed on the right dorsal musculature using a modified Hawaiian hand sling while swimming behind the *M. alfredi*. Each tag was set to operate at 69 kHz and transmit a unique acoustic signal at random intervals between 30 and 90 seconds. Before being tagged, the ventral side of each *M. alfredi* was photographed to capture their unique spot pattern for identification purposes (Marshall and Pierce, 2012), and their sex and size class (a proxy of maturity status) were recorded (Stevens, 2016). Five of the twenty *M. alfredi* that were tagged were re-sighted at their tagging locations between three and 12 days after deployment. All five were observed to be engaged in normal feeding activities (Stevens, 2016). All activities were approved by the University of Plymouth Animals in Science Ethics Committee under permit ETHICS-24-2019.

Acoustic receiver array

An acoustic array of five VR2W-69 kHz omnidirectional acoustic receivers (Vemco Inc., Nova Scotia, Canada) were deployed at depths ranging from 12 to 22 m below the sea surface on the reef flat close to the reef slope at sites corresponding to known *M. alfredi* aggregation areas around the outer rim of Egmont Atoll (Figure 1). Four of the receivers were suspended approximately 2 m above the seabed, while the fifth was attached to an oceanographic mooring 43 m above the seabed at the Manta Alley aggregation site. Acoustic tags were detected within approximately 160 m of the receivers: mean = 162 ± 31 m (SD) as determined by range testing conducted following the method described by Lea (2017).

Acoustic tag analysis

All tag detection data was imported into VUE software (version 2.6.2) and filtered for active tags. The False Detection Analyser (VUE version 2.6.2) was then used to identify false detections, whereby the ratio of short and long periods between detections is calculated from the time between detections on each receiver (Simpfendorfer *et al.*, 2015). Here, the default short to long periods of <30 min and >12 h, respectively were used (Simpfendorfer *et al.*, 2015) and all detections suspected to be false were removed from analysis. The percentage of sightings at each location were then projected in ArcGIS 10.7.

To assess whether Egmont Atoll can be considered a key habitat, residency indices (RI) were calculated using the following form (Peel *et al.*, 2019b), allowing comparison of residency patterns at Egmont Atoll between *M. alfredi* regardless of differences in tracking periods (Daly *et al.*, 2014).

$$RI(\%) = \frac{\text{Number of days detected}}{\text{Number of days between first and last detection}} \times 100$$

To assess the intensity at which locations were utilised, the amount of time each tagged *M. alfredi* spent within the detection range of each acoustic receivers was calculated using the VTrack R package (Campbell *et al.*, 2012) in R 3.5.2 (R Core Team, 2018). Briefly, each tag detection was classed as a resident or non-resident events. A resident event began when there were two or more successive detections (Nalesso *et al.*, 2019) at the same receiver within 60 minutes. Termination of the resident event occurred at the time of the last detection when there were no further detections within 60 minutes, or when the tag was detected at least twice at another receiver (Campbell *et al.*, 2012; Nalesso *et al.*, 2019).

Environmental Influences: Boosted regression trees

Boosted regression trees (BRT) were used to investigate the relationship between environmental variables and the visitation patterns of tagged *M. alfredi* to the feeding aggregation site at Manta Alley. The modelling technique is based on two algorithms: regression trees models and boosting, which build and combine large numbers of relatively small trees by fitting each new tree to the residuals of the last (Elith *et al.*, 2008). Each tree is constructed through a series of binary splits of predictor variables (Hastie *et al.*, 2009), which occur based on the homogeneity of their relationship to the response variable (Colin *et al.*, 2017). Multiple splits are tested, and partitioning occurs when the greatest improvement of homogeneity is found (Colin *et al.*, 2017). Advantages of this modelling technique include its ability to fit complex, non-linear relationships, model interactions between response variables (Elith *et al.*, 2008), and the appropriate data model does not require assumptions about the residuals of the model (Derville *et al.*, 2016).

Detection data was divided into a time-series of 5-min bins starting from 1st December 2019 and ending on 10th March 2020. The BRT was then constructed with a binomial response

of present (1) or absent (0) within each 5-min bin. The final time-series contained 28654 x 5-min bins of presence and absence observations.

Nine predictor variables representing temperature (1-2), zooplankton biomass (3), ocean currents (4-8), and tide (9), all of which have been shown to influence *M. alfredi* occurrence (O'Shea *et al.*, 2010; Anderson *et al.*, 2011; Harris *et al.*, 2020) were selected for inclusion (Table 1). Temperature variables included: temperature at 2 m above the seabed (temp 2 m) (1), and 50 m above the seabed (temp 50 m) (2), sampled every 5s using RBR Concerto CTDs. Data were pooled into the same 5-min bins as the presence and absence data. The mean temperature for each 5-min bin was then calculated from the 60 data points. For zooplankton biomass (3), acoustic backscatter was used as a proxy. Data were taken from beam 1 of the Nortek Signature 500kHz ADCP, aligned with x positive and a centre frequency of 500kHz with a bandwidth of 25kHz and retrieved from the Nortek Average AD2CP file with a sample interval of 10 mins. The instrument has a vertical resolution of 2 m per bin, and the first 25 bins were taken for data processing (0.5-50.5 m range from the instrument). The vertical profile at each time step was filtered with a running median window with a length of 3 and a maximum deviation of 1. These parameters were chosen based on observations in the data that any areas of amplified return (likely due to large targets which are not zooplankton) were constrained to the extent of a single bin due to the relatively large size of the 2 m bins when compared to the observed target size. A depth-mean value was then calculated for each time step and linearly interpolated into the 5-min bins. Ocean current data (4) included vertical velocity, for which a depth mean was calculated from the same average data and bin selection as backscatter, but with no filtering applied due to the low noise level in averaged velocity measurements. Data were then interpolated on to a 5-min time scale. Ocean current data also included the eastward (u) component at 8.5 m and 48.5 m above the

225 seabed, and northward (v) component 8.5 m and 48.5 m above the bed. Data were obtained
 226 from the Nortek Average AD2CP file, which provides a reading of component velocity at 10-
 227 min intervals; each reading covers a time period of 120 seconds and is composed of 48
 228 independent samples (0.4 Hz), giving an overall measurement uncertainty of $<1 \text{ cm s}^{-1}$ for
 229 horizontal velocity measurements. Ten-min data were interpolated onto a 5-min timescale
 230 using linear sampling. Each variable is representative of a single 2 m depth bin, chosen to be
 231 safely out of the influence range for ringing and sidelobe interference (5.5m and 45.5 m from
 232 the transducer, respectively). Both u and v velocity components were then rotated clockwise
 233 117° relative to north, to align with the slope in Manta Alley (adjusted positive and negative
 234 directions, shown in Figure 3), resulting in the ocean current predictor variables: cross-shore
 235 current at 48.5 m above the bed (CS current (v) 48.5 m) (5), cross-shore current at 8.5 m above
 236 the bed (CS current (v) 8.5 m) (6), longshore current at 48.5 m above the bed (LS current (u)
 237 48.5 m) (7), and longshore current at 8.5 m above the bed (LS current (u) 8.5 m) (8). To
 238 estimate tidal phase, pressure data was taken from the lower RBR Concerto CTD (depth 64.1
 239 m) and converted to depth data using RSKTools inbuilt conversion function. Data were
 240 cleaned with a median filter and averaged with a running window (both size 501 points). The
 241 Matlab inbuilt find peaks function was then used and ran twice to pick out both high and low
 242 tides by inverting the data on one run. A 5.5 h minimum peak spacing was specified to further
 243 reduce susceptibility to noise, and the resulting data points were visually validated against
 244 the raw depth data. The variable time relative to high tide (9), was then calculated with high
 245 tide as zero and negative hours before (flood) and positive hours after (ebb) (Peel *et al.*,
 246 2019b).

247 All models were fitted using the `gbm.step()` function of the `dismo` R package (Hijmans
 248 *et al.*, 2017). Initial models were built to find suitable settings for four parameters: tree

complexity (tc), which specifies the number of interactions that should be modelled, learning rate (lr), which regulates the contribution of each tree to the growing model, bag fraction (bf), which controls stochasticity by randomly selecting (without replacement) a specified subset of the data at each iteration and step size (ss), which controls the number of trees which should be added at each iteration (Elith *et al.*, 2008). The following parameter settings were tested: $tc = 1-6$, $lr = 0.01, 0.005, 0.001$ and 0.0001 , $bf = 0.5, 0.7, 0.9$, $ss = 25$ and 50 , resulting in 144 models.

Ten-fold cross-validation (CV) was applied to assess model performance, whereby the model is fitted to training data and then is tested against a withheld portion (hold-out sample) of the dataset (Elith *et al.*, 2008). The model's ability to fit the withheld data was then measured by comparing the area under the receiver operating characteristic curve (AUC) test statistic (Froeschke *et al.*, 2010; Dedman *et al.*, 2017) for both the training data (τ AUC) and hold-out sample (cross-validation AUC, c_v AUC) (Dedman *et al.*, 2017; Elith and Leathwick, 2017). The AUC classification ranges from 0 - 1, whereby: < 0.5 (fail), $0.6 - 0.7$ (poor), $0.7 - 0.8$ (acceptable), $0.8 - 0.9$ (excellent), > 0.9 (outstanding) (Hosmer and Lemeshow, 2000). The difference between the τ AUC and the c_v AUC (Δ AUC) indicates the level of overfitting of the primary sample (Dedman *et al.*, 2017). Therefore, better model performance is categorised by higher AUC values for both τ AUC and c_v AUC, but a lower Δ AUC (Dedman *et al.*, 2017).

The percentage of deviance explained by the model was determined using the pseudo determination coefficient (D^2), calculated using the following form (Nieto and Mélin, 2017):

$$D^2 = 1 - (\text{residual deviance} / \text{total deviance})$$

The final model was fitted with $tc = 6$, $lr = 0.005$, $bf = 0.7$, and $ss = 50$ (Table S2). The relative contribution of predictor variables to the BRT model is measured by averaging the

number of times a variable is chosen for splitting and the squared improvement resulting from these splits (scaled to 100 across all the variables) (Elith *et al.*, 2008). To ensure non-informative predictors were not hindering model performance, pairwise correlation coefficients and variance inflation factor (VIF) estimates (Jouffray *et al.*, 2019) were calculated, all were in an acceptable range; coefficients < 0.6 and/or VIF estimates < 3.5 (Jouffray *et al.*, 2019) (Table S1 and Figure S1).

Due to the complex nature of BRTs, model results cannot be easily visualised. Therefore, partial dependency and interaction plots were generated for interpretation. The plots display the results of the predicted effect on tag detection probability for a given predictor, or pair of predictors, after accounting for the mean effects of all other predictors (Elith *et al.*, 2008; Hastie *et al.*, 2009). Confidence intervals (95%) for the partial dependency plots were obtained from 1000 bootstrap replicates (Jouffray *et al.*, 2019). For interaction plots, 100 bootstrap resampling was used to test the significance of the strongest interactions (Pinsky and Byler, 2015; Jouffray *et al.*, 2019) (interaction strength > 100) by randomly sampling the occurrence of *M. alfredi* at each location before re-fitting the BRT models (Jouffray *et al.*, 2019). The size of the interaction was then used to generate a distribution under the null hypothesis of no interaction among predictors (Jouffray *et al.*, 2019).

Results

Detection and resident event summary

Acoustic transmitter tags were deployed on eleven female (adults = 5, sub-adults = 4, juvenile = 2) and nine male (adults = 3, juvenile = 6) *M. alfredi* (Table 2). Nineteen of the 20 tags returned useable tracks (Table 2). No detections have been recorded for three of the 19 tags since 21st November 2019 (CG-MA-0120), 27th December 2019 (CG-MA-0161), and 20th

January 2020 (CG-MA-0141). However, it is not possible to distinguish between acoustic tag loss and emigration from the study area, and relatively long temporal gaps between detections of *M. alfredi* in the Chagos Archipelago have previously been reported (Andrzejaczek *et al.*, 2020). Therefore, the current status of these tags has been recorded as ‘unknown’ rather than ‘inactive’, pending further data collection.

There were a total of 15965 detections during the study period (Table 2). The highest percentage of detections occurred at the acoustic receiver deployed on the oceanographic mooring in Manta Alley (51.4%), followed by North IdR Cleaning Station (22.3%) (Figure 4).

The overall distribution of detections by hour of the day shows 70.9% of detections occurred at Egmont Atoll during the day (06:00-18:00) (Figure 5). For adults, only 18.3% of detections occurred at night (19:00-05:00), while 35% of detections occurred at night for juveniles.

The mean total time between tag deployment when the tags first began transmitting until the end of the study, when the detection data was downloaded was 113 ± 5 day (range 106-119 days). During this time, tagged *M. alfredi* were tracked (first to last tag detection) for a mean of 97 ± 32 days (range 3 – 116 days), with a mean of 50 ± 23 detection days (range 2-92 days). Residency indices show that tagged *M. alfredi* were detected at Egmont Atoll for a mean of 52% of the days they were tracked ($RI = 52 \pm 15.7\%$), with a minimum and maximum RI of 24% and 80.3%, respectively (Table 2). Mean residency indices were similar for both adults and juveniles (including sub-adults), which were $53 \pm 16\%$ and $51 \pm 16\%$, respectively.

Overall, 2074 resident events were recorded for 19 *M. alfredi* (Figure 6). The highest number of resident events occurred at Manta Alley (837), totalling 22188 mins (369.8 hrs). Manta Alley also had the longest individual mean resident event time (27 ± 51 , Table 3), with

the longest resident event of 489 min (8.2 hrs) by a juvenile male (manta-ID CG-MA-0125). Of the 837 resident events, a total of 35 lasted >120 mins, of which 11 were female (adult = 5, juvenile = 6) and 24 were males (adult = 3, juvenile = 21).

The lowest number of residency events occurred at Ile Sudest (41), totalling 191 mins (3.1 hrs). Mean resident event time was 5 ± 10 mins, with a maximum resident event time of 56 mins by an adult male (manta-ID CG-MA-0161).

Environmental Influences: Boosted regression trees

Model performance evaluation for the BRT, including all nine predictors, had outstanding and excellent predictive performance for the training (τ AUC = 1) and cross-validated (c_v AUC = 0.89) data, respectively, with minimal evidence of overfitting (Δ AUC = 0.11). The estimated D^2 suggests that 72 % of the deviance was explained (Table S2).

Partial dependency plots (Figure 7) indicate that the probability of detections decreased with increased near-bed temperature (temp 2 m, 16.2%), and increased with increased backscatter strength (13.3%) and near-surface temperature (temp 50 m, 13.3%). Detection probability was higher with greater downward vertical velocity (12.8%), and during the early stages of a flood tide (12.1%), approximately two hours following low tide when near-surface longshore current velocity (longshore (v) 48.5 m, 11.7%) was approximately 0.2 ms^{-1} near the surface and 0.3 ms^{-1} near the seabed (longshore (v) 8.5 m, 9.1%). For cross-shore currents, detection probability increased when near-surface currents were flowing offshore (cross-shore (u) 48.5 m, 6.1%) at approximately -0.05 m s^{-1} , and when near-bed currents (cross-shore (u) 8.5 m, 5.4%) were flowing inshore at approximately 0.15 ms^{-1} .

Eight significant pairwise interactions occurred between eight predictors (Table 4 and Figure S2). These interactions should not be considered in isolation, as they may arise separately or simultaneously, and may be affected by other variables. However, they provide insight into the estimated influence of several paired-environmental processes which can increase the probability of tag detections. For example, tag detections probability was highest when upward currents speed (vertical velocity) was increased, and the near-surface temperature (Figure S2a) was warmer (temp 50 >29.5°C). Tag detection probability also increased with cooler near-bed temperature (temp 2 m <24°C), and increased near-surface temperatures (temp 50 m >29.5°C) (Figure S2b). It also increased when near-bed cross-shore currents (cross-shore (u) 8.5 m) were of a high +ve velocity (>0.15ms⁻¹) (flowing into the lagoon) and backscatter was > 55 (Figure S2c), and with high temp 2 m (> 29°C) and backscatter > 55 (Figure S2d).

Discussion

Overall, *M. alfredi* residency at Egmont Atoll, measured by the residency index (RI), was high (mean RI =52%), which supports previous reports that Egmont Atoll provides key habitats for this species (Harris, 2019; Andrzejczek *et al.*, 2020). Similar high levels of residency have been observed in the Red Sea (mean RI = 65%) (Braun *et al.*, 2015) and at the Amirante Islands of Seychelles (mean RI = 62%) (Peel *et al.*, 2019b). Adult and juvenile *M. alfredi* displayed similar residency at Egmont Atoll, which is in contrast to patterns observed in Seychelles, where the RI was lower for adults (Peel *et al.*, 2019b), indicating that the *M. alfredi* habitat at Egmont Atoll is perhaps consistently important for all life stages. Alternatively, the similar residency of adults and juveniles could be attributed to the acoustic array design (Peel *et al.*, 2019b). To establish a more robust RI, future research would benefit

from increased spatial coverage, including the deployment of acoustic receivers in locations which may be frequented by juveniles such as inside the lagoon.

Overall, detection data displays diel behaviour patterns, with the highest percentage of detections at Egmont Atoll occurring during the day. Similar diel patterns have been recorded during studies of various *M. alfredi* subpopulations, where individuals frequented shallow coastal and island reef systems more often during daylight hours (Dewar *et al.*, 2008; Jaine *et al.*, 2012; Couturier *et al.*, 2018; Setyawan *et al.*, 2018; Peel *et al.*, 2019b). These patterns may be associated with the species use of cleaning stations, where cleaner fish are only active during the day (Côté, 2000). Diel movement patterns may also be associated with efficient foraging strategies. For example, *M. alfredi* may predominately frequent shallow reef habitats during the day to feed on reef-associated zooplankton which can accumulate in surface waters over shallow reefs when avoiding predation from reef-dwelling diurnal consumers (Alldredge and King, 2009; Leichter *et al.*, 2013). At night, *M. alfredi* may then travel offshore to forage (Dewar *et al.*, 2008; Jaine *et al.*, 2012; Couturier *et al.*, 2018) when diel vertically migrating zooplankton ascends into warmer water (Dewar *et al.*, 2008; Braun *et al.*, 2014; Couturier *et al.*, 2018). This hypothesis is supported by stable isotope analysis, which indicates that a large proportion of *M. alfredi* diet is made up of both near-surface and demersal zooplankton (Couturier *et al.*, 2013b; Peel *et al.*, 2019a). The diel *M. alfredi* movement pattern was less pronounced for juveniles, which were more frequently detected at night than adults, suggesting that juvenile *M. alfredi* remain in shallower reef habitats longer. This pattern has also been observed in other subpopulations and is likely a predator avoidance strategy by the more vulnerable juveniles (Cerutti-Pereyra *et al.*, 2014; Stewart *et al.*, 2018; Peel *et al.*, 2019b). Their smaller body size may also make it less energetically

efficient for juveniles to travel offshore (Nøttestad *et al.*, 1999; Peel *et al.*, 2019b), and/or their foraging experience may be limited (Peel *et al.*, 2019b).

Manta Alley had the highest number of detections, and there were repeated resident events for 18 of the 19 tagged individuals, indicating a high level of site fidelity. Site fidelity is a well-reported characteristic of *M. alfredi*, having been observed in photographic identification, acoustic telemetry and satellite tagging studies (Dewar *et al.*, 2008; Deakos, 2011; Jaine *et al.*, 2014; McCauley *et al.*, 2014; Stevens, 2016; Kessel *et al.*, 2017; Couturier *et al.*, 2018). Site fidelity has been attributed in part to the species' reliance on specific habitats, which provide a sufficient food resource, protection from predation, and opportunities to clean, socialise and reproduce (Jaine *et al.*, 2014; McCauley *et al.*, 2014; Stevens, 2016; Perryman *et al.*, 2019). Resident events were longer at Manta Alley than at any other location. The depth of the majority of the area within the range of the acoustic receiver is greater than 40 m. As 40 m is the maximum depth of occurrence for cleaner fish in the Chagos Archipelago (Kuitert, 2014), it is unlikely that these extended resident events at Manta Alley are associated with cleaning activities. Furthermore, in-water observations at this site by the authors during this study observed large *M. alfredi* aggregations feeding (~40 individuals) on the surface down to 20 m on several occasions, while no cleaning stations were identified. Therefore, the most likely driver of the visitation patterns recorded for *M. alfredi* at this site during this study is foraging opportunities. For *M. alfredi* foraging activities to be energetically efficient, high densities of prey are required (Armstrong *et al.*, 2016). The BRT model suggests that *M. alfredi* presence at Manta Alley is associated with various fine-scale oceanographic processes, which could be combining to enhance localised zooplankton abundance.

A high tag detection probability of *M. alfredi* occurred with cold near-bed and warm near-surface temperature, and probability increased with increasing difference between these temperatures. Extreme short-term fluctuations in near-bed temperatures may be associated with the intrusion of cold-water created by internal waves which disrupt the thermocline (Shanks *et al.*, 2014). Enhanced concentrations of zooplankton often occur at the thermocline, the thickness of which can be increased by internal waves (McManus *et al.*, 2005). These internal waves break as they interact with the steep slope of an atoll leading to the formation of cold-water bores which propagate up the slope (Woodson, 2018; Hosegood *et al.*, 2019). Bores enhance the upward transport of organisms, and thus the concentration in surface waters (Stevick *et al.*, 2008), which may provide efficient foraging opportunities for the zooplanktivorous *M. alfredi*. The upward propagation of cold-water bores has been observed to vary tidally (Leichter *et al.*, 1996; Hosegood *et al.*, 2019), and can become more frequent during a flood tide leading to a pulsed delivery of organisms (Leichter *et al.*, 1996; Woodson, 2018). Here, tag detection probability was high during the early stages of a flood tide, and was also increased by the interaction effect between a flood tide and cooler near-surface temperature, which may indicate that cold-water bores propagate up the slope (Leichter *et al.*, 1996). Plankton sampling and oceanographic measurements obtained inside the lagoon also indicate that increased zooplankton abundance is associated with the transfer of plankton into the lagoon from the intrusion of cold water-bores created by breaking internal waves (Sheehan *et al.*, 2019). The intrusion of cold water may also provide metabolically advantageous feeding conditions for *M. alfredi* by reducing the energetic cost of feeding activities (Lawson *et al.*, 2019)

In the current study, tag detection probability also increased with the interaction between high-velocity near-bed cross-shore currents flowing inshore and high levels of

backscatter. This interaction may indicate that zooplankton is being carried from the thermocline into the lagoon during a flood tide and is likely pumped back out during ebb. Due to the partially enclosed morphology of the lagoon, water entering is likely to be restricted by the narrow subtidal passages. Even with a low tidal amplitude, strong jet-like currents can be generated (Dumas *et al.*, 2012), which may increase the density of inflowing (outflowing) zooplankton approaching low tide (in the early stages of flood), as suggested by the in-water observations of the current study. During these events, mobile zooplankton may actively seek refuge zones to avoid predation or import into (export from) the lagoon (Pagano *et al.*, 2017). Refuge zones include the thermocline and behind shallow back reefs (Leichter *et al.*, 2013), where zooplankton become concentrated further, providing dense assemblages of prey for *M. alfredi*. Similar theories of zooplankton retention, which are also related to tide phase, have been suggested in other regions (Armstrong *et al.*, 2016; Stevens, 2016).

The BRT also provided some evidence of the presence of Langmuir Circulation (LC), which can trap and concentrate particles in the water column (Smith, 2001). The process is driven by wind and waves which produce helical vortices that appear as rotating cells that rotate perpendicular to the wind direction (Smith, 2001). The interaction effect between high velocity near-bed longshore currents flowing when near-surface currents were flowing in the opposite direction, and high backscatter intensity could be evidence of LC cells. Alternating cells rotate in opposite directions leading to areas of convergence and divergence (Talley *et al.*, 2011). Downwelling, which increased the probability of tag detections, occurs in areas of convergence where plankton, other organisms, and particles become trapped in highly concentrated bands (Kingsford *et al.*, 1991; Thorpe, 2004). These bands may provide ideal foraging opportunities for *M. alfredi*. As LC can persist for hours or even days (Gargett *et al.*, 2004), it could potentially be associated with resident events which last longer than the

influence of the tide (>2 hours). The characteristic surface 'slicks' which often accompany LC have also been regularly observed by authors in Manta Alley, further supporting this suggestion.

Under well-mixed conditions, LC can develop 'super-cells' which extend the full depth of the water column (Gargett *et al.*, 2004). These super-cells can transport organisms and particles from depths up into the water column where they become concentrated in the narrow bands of the convergence zones (Gargett *et al.*, 2004; Kukulka *et al.*, 2012). Potential evidence of the presence of super-cells and their positive influence on *M. alfredi* detection probability is apparent with the interaction effects between high near-bed temperature near-bed temperature (>28.5°C) and lower near-surface temperature (28-28.5°C), indicating a well-mixed water column, warmer near-bed temperature (>28.5°C), and high backscatter, and increased downward vertical velocity (downwelling) and low near-surface temperatures (<28.5°C). However, high backscatter could also be caused by sediment resuspension events which can be induced by LC super-cells (Gargett *et al.*, 2004). There may be evidence of the effect of LC on *M. alfredi* visitation and behaviour patterns in other regions. For example, in Komodo Marine Park in Indonesia, *M. alfredi* were observed feeding where there were surface slicks and a high density of particles in the water column (Dewar *et al.*, 2008), which is characteristic of LC convergence zones (Kingsford *et al.*, 1991). Around Lady Elliot Island (LEI) in Australia, sightings of foraging individuals and increased acoustic tag detection were correlated with wind speed (Jaine *et al.*, 2012; Couturier *et al.*, 2018). At LEI, *M. alfredi* sightings and tag detections peaked at wind speeds around 18 km.h⁻¹ (approximately 5ms⁻¹), an optimal speed for the development of LC (Langmuir, 1938; Plueddemann *et al.*, 1996). At LEI, sightings were also associated with cooler sea surface temperatures, with a decrease in sightings and detections with increased temperature (Jaine *et al.*, 2012; Couturier *et al.*,

2018). Strong surface warming can lead to a breakdown of LC by disrupting the balance between wave-forcing and thermal convection (density-driven circulation) (Li and Garrett, 1994; Min and Noh, 2004), which may reduce the density of prey, leading to a lower number of sightings and tag detections of *M. alfredi*.

There were some limitations to the current study. For example, the position of tagged *M. alfredi* in the water column and the distance the individual was from the acoustic receiver and oceanographic equipment could not be established. The acoustic doppler current profiler (ADCP) was also deployed on the edge of the range of the acoustic receiver. Therefore, it is possible that some of the changes in the oceanographic conditions which influence *M. alfredi* visitation patterns were not fully resolved here. These limitations may be mitigated in future by using acoustic transmitters which also deliver distance and depth information when the individual is detected. A reconfiguration of the mooring to include an ADCP in line with all other sensors would also be beneficial. Future research would also benefit from oceanographic monitoring within the lagoon passage and the Manta Alley feeding location concurrently to help further resolve the fine-scale processes occurring at the lagoon-ocean interface. Further investigation into the potential presence of LC and its influence on *M. alfredi* visitation patterns at Manta Alley is also required. Research should incorporate *in situ* wind directions measurements of the same spatial and temporal resolution as the longshore and cross-shore current directions. These measurements should be accompanied by ADCP backscatter data to detect zones of high echo intensity and periods of downwelling in relation to *M. alfredi* visitation patterns, and plankton sampling to assess the content of the water column during LC events.

Studying *M. alfredi* at Egmont Atoll provides valuable insight into how the species respond to fine-scale changes in their oceanographic environment, thus improving our current knowledge of *M. alfredi* foraging ecology. Evidence provided in this study suggests that the species regularly take advantage of feeding opportunities which are influenced by fine-scale oceanographic processes that occur close to the lagoon-ocean interface. These feeding opportunities appear to occur with tidal periodicity. During a flood tide, cold-water bores frequently propagate up the slope, transporting zooplankton from the thermocline into the lagoon through the narrow inlet. During an ebb tide, the zooplankton then flows back out of the lagoon with the highest concentrations occurring close to low tide. Mobile zooplankton may become trapped and concentrated around reef structures as they attempt to avoid predation by moving back into deeper water. High concentrations of zooplankton which occur during these tidal phases are likely to be short-lived, occurring in pulses, providing temporally limited feeding opportunities for *M. alfredi*. However, under suitable conditions, for example, in the presence of LC, highly concentrated bands of zooplankton may persist for hours, potentially providing extended feeding opportunities which result in *M. alfredi* spending long periods of time at the location.

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Table 1: Description of the predictor variables used in boosted regression trees analysis of tagged *Mobula alfredi* occurrence at Manta Alley. All predictors are in 5-min means unless otherwise specified. All distances are metres above the seabed. Mean values show the value at which the predictor is held for partial dependency and interaction plots.

Predictor No.	Predictor	Unit	Mean	Description
1	Temp 2 m	°C	27.7	Temperature 2 m above the bed (depth 64.1 m)
2	Temp 50 m	°C	29.1	Temperature 50 m above the bed (depth 13.4 m)
3	Backscatter	dB	46.1	Depth-mean linearly interpolated into 5-min bins
4	Cross-shore (v) 48.5 m	ms ⁻¹	-0.007	Surface current 48.5 m above the bed (depth 17.6 m) flowing 27° (-ve) and 207° (+ve) relative to N
5	Cross-shore (v) 8.5 m	ms ⁻¹	-0.016	Near bed current 8.5 m above the bed (depth 57.6 m) flowing 27° (-ve) and 207° (+ve) relative to N
6	Longshore (u) 48.5 m	ms ⁻¹	-0.095	Near surface current 48.5 m above the bed (depth 17.6 m) flowing 117° (-ve) and 297° (+ve) relative to N
7	Longshore (u) 8.5 m	ms ⁻¹	-0.078	Near bed current 8.5 m above the bed (depth 57.6 m)

				m) flowing 117° (-ve) and
				297° (+ve) relative to N
				Upward (+ve) and
8	Vertical velocity	ms ⁻¹	0.002	downward (-ve) current
				flow.
9	Time to high tide	0.083 h	0.014	Time relative to high tide in
				steps of 5-min (0.083h) with
				high tide zero, negative
				values before (flood) and
				positive values after (ebb).

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838 **Table 2:** Summary of *Mobula alfredi* acoustic tag deployments (n=19), tracking, detections and Residency Index (RI) for Egmont Atoll. Status refers to the known status of
 839 tags at the time of last detection data download (17th March 2020).

Manta ID	Sex	Maturity status	Tag ID	Deployment Date	Deployment Location	Lat	Long	Last Detection	Total No. of Detection	Tracking Days	Detection Days	Residency Index (RI%)	Status
CG-MA-0035	F	Sub-adult	18890	20/11/2019	Ile Sipaille	-6.67	71.32	13/03/2020	1159	115	92	80	ACTIVE
CG-MA-0046	F	Adult	18892	25/11/2019	Ile Tattamucca	-6.69	71.38	10/03/2020	846	107	61	57	ACTIVE
CG-MA-0070	F	Adult	18891	01/12/2019	Ile Lubine	-6.67	71.32	17/03/2020	1059	108	46	43	ACTIVE
CG-MA-0088	M	Juvenile	18897	28/11/2019	Ile Lubine	-6.67	71.32	15/03/2020	907	109	43	40	ACTIVE
CG-MA-0094	F	Sub-adult	18894	30/11/2019	Ile Sipaille	-6.66	71.31	13/03/2020	1116	105	67	64	ACTIVE
CG-MA-0112	M	Juvenile	18893	01/12/2019	Ile Lubine/Sipaille	-6.66	71.31	13/03/2020	1129	104	49	47	ACTIVE
CG-MA-0117	F	Sub-adult	18887	20/11/2019	Ile Lubine	-6.67	71.32	13/03/2020	718	115	50	44	ACTIVE
CG-MA-0118	M	Juvenile	18900	19/11/2019	Ile Sipalle	-6.66	71.31	11/03/2020	678	114	41	36	ACTIVE
CG-MA-0119	F	Juvenile	18901	19/11/2019	Ile Sipalle	-6.67	71.32	13/03/2020	801	116	54	47	ACTIVE
CG-MA-0120	F	Adult	18902	19/11/2019	Ile Sipalle	-6.67	71.32	21/11/2019	15	3	2	76	UNKNOWN
CG-MA-0121	M	Juvenile	18903	19/11/2019	Ile Sipalle	-6.67	71.32	13/03/2020	1770	116	84	73	ACTIVE
CG-MA-0124	M	Adult	18885	20/11/2019	Ile Lubine	-6.67	71.32	12/03/2020	559	114	44	39	ACTIVE
CG-MA-0125	M	Juvenile	18895	20/11/2019	North IDR Cleaning St	-6.64	71.32	14/03/2020	1272	116	60	52	ACTIVE
CG-MA-0139	F	Adult	18899	25/11/2019	Ile Tattamucca	-6.69	71.38	15/03/2020	763	112	73	66	ACTIVE
CG-MA-0140	M	Juvenile	18898	30/11/2019	North IDR Cleaning St	-6.64	71.32	13/03/2020	711	105	25	24	ACTIVE

CG-MA-0141	F	Adult	18889	28/11/2019	Ile Lubine	-6.67	71.32	20/01/2020	411	54	31	58	UNKNOWN
CG-MA-0142	F	Sub-adult	18884	02/12/2019	Ile Tattamucca	-6.70	71.40	15/03/2020	1216	105	59	56	ACTIVE
CG-MA-0151	M	Adult	18896	01/12/2019	Ile Lubine	-6.68	71.33	12/03/2020	794	103	62	60	ACTIVE
CG-MA-0161	M	Adult	18888	02/12/2019	Ile Carre Pate	-6.68	71.35	27/12/2019	41	26	7	27	UNKNOWN

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851 **Table 3:** Summary of acoustic receiver deployment locations, recording times and resident event durations.

Location	Deployed	Lat	Long	Depth (m)	Height above seabed (m)	No. days recording	No. <i>M.</i> <i>alfredi</i>	Mean resident event (min±SD)	Max resident event (mins)
Ile Sipaille	19/11/2019	71.32	-6.67	14.6	1.5	116	19	15±26	200
Ile Sudest	01/12/2019	71.40	-6.70	15	1.8	104	11	5±10	56
Manta Alley	30/11/2019	71.35	-6.64	70	48	109	18	27±51	489
North IdR Cleaning Station	19/11/2019	71.32	-6.64	13.6	1.6	116	17	19±36	294
South Manta Alley	30/11/2019	71.39	-6.67	14.2	1.8	105	18	16±26	133

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857 **Table 4:** Pairwise interactions between predictor variables with all other variables held to their respective mean (Table 1). Higher interaction size values indicate a more
858 substantial interaction effect; near zero indicates negligible interactions. All interactions were significant ($p<0.01$). The suggested influence of the interaction on the
859 probability of detections is described along with the maximum detection probability estimated for each interaction.

Plot	Predictor 1	Predictor 2	Interaction size	Nature of interaction increasing tag detection probability	Max detection probability (%)
S2a	Temp 50 m	Vertical velocity	768.77	Warmer near-surface temperature and increased upward vertical velocity.	90
S2b	Temp 50 m	Temp 2 m	741.86	Cooler near-bed temperature and increased near-surface temperature indicating the water column is stratified. Warmer near-bed temperature (>28.5°C) with similar near-surface temperature (28-28.5°C)	92
S2c	Cross-shore (v) 8.5 m	Backscatter	427.88	Near-bed longshore currents flowing at velocity of >0.15ms ⁻¹ (+ve, flowing into the lagoon) and high backscatter intensity (>55).	85

S2d	Temp 2 m	Backscatter	405.69	Warmer near-bed temperature ($>29.5^{\circ}\text{C}$) and high backscatter intensity (>55).	98
S2e	Longshore (u) 8.5 m	Time to high tide	165.86	During the early stages of flood with increasing near-bed longshore current velocity (+ve, flowing from North IdR Cleaning Station towards South Manta Alley) flowing from the	86
S2f	Longshore (u) 48.5 m	Time to high tide	124.66	During the early stages of flood with moderate velocity (approximately $0.3\text{--}0.4\text{ ms}^{-1}$) longshore near-surface current (+ve, flowing from North IdR Cleaning Station towards South Manta Alley)	66
S2g	Temp 50 m (53%)	Time to high tide	182.1	During the early stages of flood with cooler near-surface temperature ($<29^{\circ}\text{C}$) and during ebb close to low tide with warmer near-surface temperature ($>29.5^{\circ}\text{C}$).	59
S2h	Longshore (v) 8.5 m	Backscatter	100.63	Longshore near-bed currents flowing at moderate to the maximum speed observed (-0.66 ms^{-1}) from South Manta Alley towards North IdR Cleaning Station, and high backscatter intensity (>55).	73

Figure 1: The Central Indian Ocean with Chagos Archipelago; British Indian Ocean Territory indicated within the red box (left inset). The Chagos Archipelago with Egmont Atoll indicated within the red box (left). Egmont Atoll and the location of the oceanographic and acoustic receiver mooring in Manta Alley (red and yellow dots) and four acoustic receivers (green dots) (top right). Bathymetric view of Manta Alley obtained via multibeam survey (Robinson and Hosegood *et al.*, unpublished data) showing the location of the moorings (bottom right). Bottom right legend showing instrument configurations of the long thermistor string (red dot/pin) and subsurface ADCP moorings (yellow dot/pin) deployed 182 m apart anchored at a depth of 66 m. Z is the height above the seabed.

Figure 2: Reef manta rays (*Mobula alfredi*) engaged in feeding activities at the Manta Alley feeding aggregation site in north Egmont Atoll. Photo by Simon Hilbourne, Manta Trust.

Figure 3: Original current u and v components (yellow dashed lines) and after clockwise rotation 117° relative to north (white lines). Arrows on the white lines show the direction of longshore u (LS U-ve and LS U+ve) and cross-shore v (CS V-ve and CS V+ve). Showing mooring locations: long thermistor string (red dot) and subsurface ADCP moorings (yellow dot).

Figure 4: Percentage of detections at each site.

Figure 5: Percentage distribution of detections by hour of the day at Egmont Atoll for all tagged *M. alfredi* (left), adults only (middle) and juveniles only (right).

Figure 6: Resident events at each site showing location (by colour) and time at the location (by size).

Figure 7: Partial dependency plots showing the effect of each predictor variable: temperature 2 m above the bed (Temp 2 m), depth-mean backscatter intensity linearly (Backscatter),

883 temperature 50 m above the bed (Temp 50 m), upward (+ve) and downward (-ve) current
884 flow (Vertical velocity), time relative to high tide in steps of 5-min (0.083h) with high tide zero,
885 negative values before (flood) and positive values after (ebb) (Time to high tide), near-surface
886 current 48.5 m above the bed (depth 17.6 m) flowing 117° (-ve) and 297° (+ve) relative to N
887 (Longshore (u) 48.5 m), near bed current 8.5 m above the bed (depth 57.6 m) flowing 117° (-
888 ve) and 297° (+ve) relative to N (Longshore (u) 8.5 m), near-surface current 48.5 m above the
889 bed (depth 17.6 m) flowing 27° (-ve) and 207° (+ve) relative to N (Cross-shore (v) 48.5 m),
890 near bed current 8.5 m above the bed (depth 57.6 m) flowing 27° (-ve) and 207° (+ve) relative
891 to N (Cross-shore (v) 8.5 m), on the occurrence of tagged *M. alfredi* at Manta Alley while
892 keeping all other variables at their mean. The green line shows smoothed partial decency.
893 Rugs display the distribution of the data for presence (top, blue), and absence (red, bottom).

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895 **Data Accessibility**

896 The data that supports these findings are available from FigShare (doi:
897 10.6084/m9.figshare.13139309) following a one-year embargo from the date of publication
898 to allow for further publication of research findings.

899

900 **Competing Interests**

901 There are no competing financial, professional, or personal interests that might have
902 influenced the performance or presentation of the work described in this manuscript.

903 **Author contributions**

904 **Joanna L. Harris:** Conceptualisation; data curation; formal analysis; investigation;
905 methodology; project administration; software; visualisation; writing – original draft
906 preparation; writing – review & editing. **Phil Hosegood:** Conceptualisation; investigation;
907 project administration; supervision; writing – review & editing. **Edward Robinson:** Data
908 curation; software; investigation; writing – review & editing. **Clare B. Embling:** Supervision;
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910 **M. W. Stevens:** Conceptualisation; supervision; writing – review & editing.

911

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921

922 **Authors' Contributions**

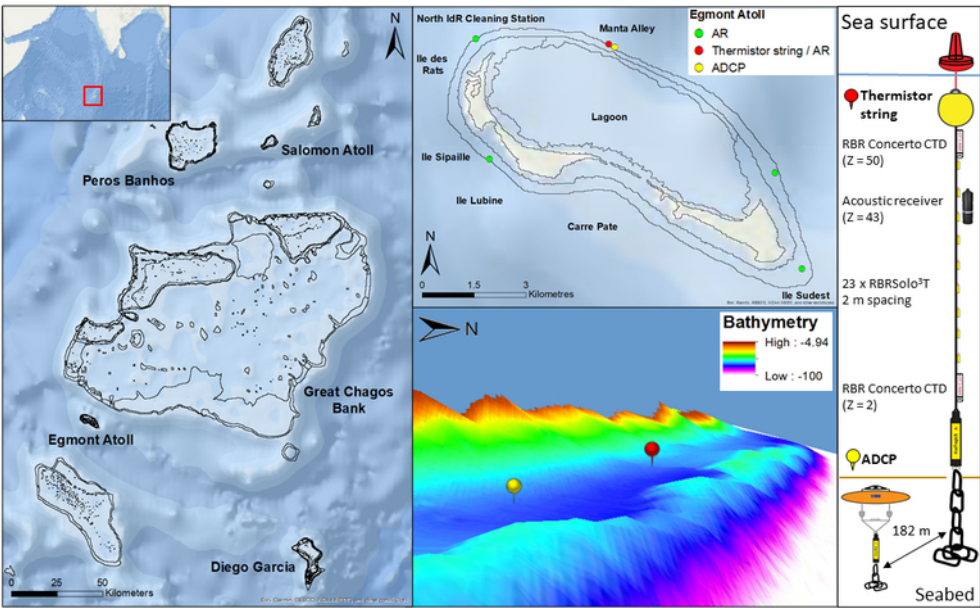
923 Joanna Harris: Conceptualization-Lead, Data curation (lead); Formal analysis (lead);
924 Investigation (lead); Methodology (lead); Writing-original draft (lead); Writing-review &
925 editing (lead). Phil Hosegood: Conceptualization (supporting); Funding acquisition (equal);
926 Investigation (supporting); Project administration (lead); Supervision (equal); Writing-review

927 & editing (supporting). Edward Robinson: Data curation (supporting); Investigation
928 (supporting); Software (supporting); Writing-review & editing (supporting). Clare Embling:
929 Supervision (equal); Writing-review & editing (supporting). Simon Hilbourne: Investigation
930 (supporting); Writing-review & editing (supporting). Guy Stevens: Conceptualization
931 (supporting); Funding acquisition (equal); Supervision (equal); Writing-original draft
932 (supporting); Writing-review & editing (supporting).

933

934 **Conflict of Interest.**

935 None declared.



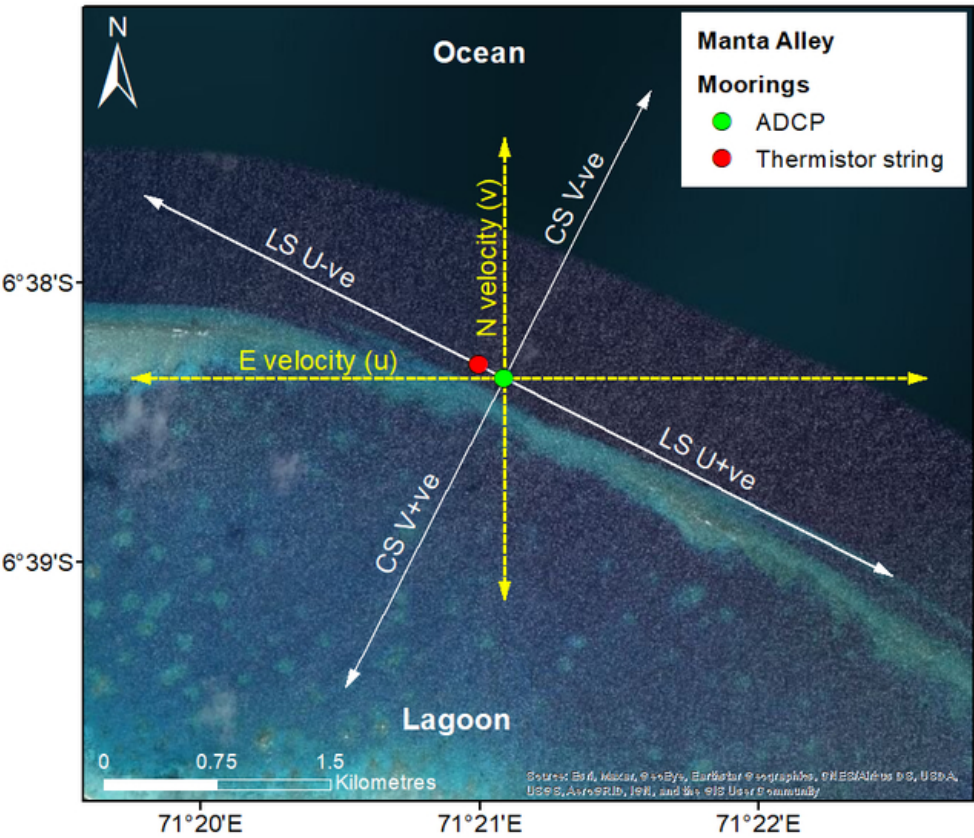
The Central Indian Ocean with Chagos Archipelago indicated within the red box (left inset). The Chagos Archipelago with Egmont Atoll indicated within the red box (left). Egmont Atoll and the location of the oceanographic and acoustic receiver mooring in Manta Alley (red and yellow dots) and four acoustic receivers (green dots) (top right). Bathymetric view of Manta Alley obtained via multibeam survey (Robinson and Hosegood *et al.*, unpublished data) showing the location of the moorings (bottom right). Bottom right legend showing instrument configurations of the long thermistor string (red dot/pin) and subsurface ADCP moorings (yellow dot/pin) deployed 182 m apart anchored at a depth of 66 m. Z is the height above the seabed.

33x22mm (600 x 600 DPI)



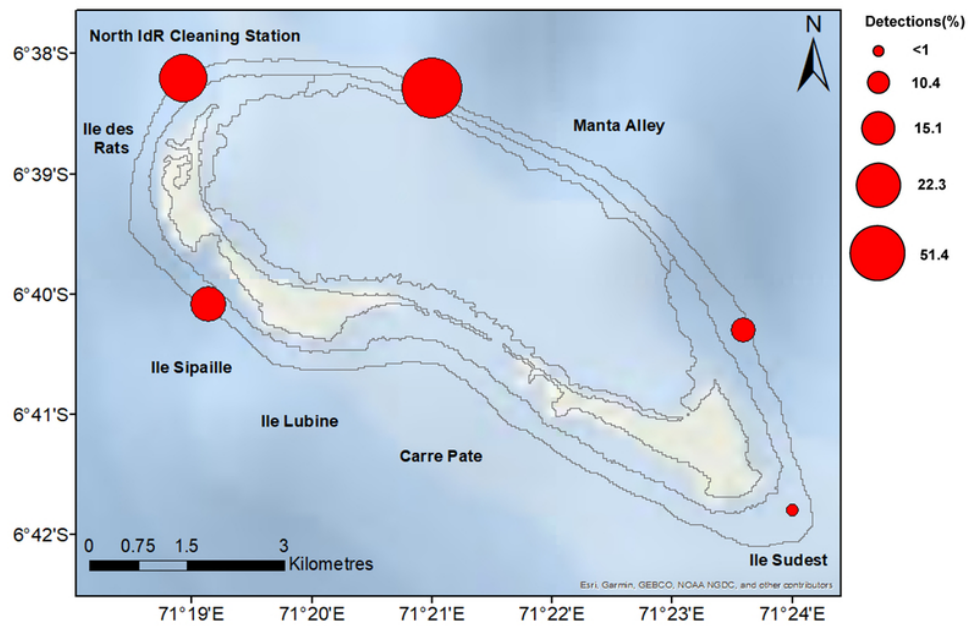
Reef manta rays (*Mobula alfredi*) engaged in feeding activities at the Manta Alley feeding aggregation site in north Egmont Atoll.

169x113mm (600 x 600 DPI)



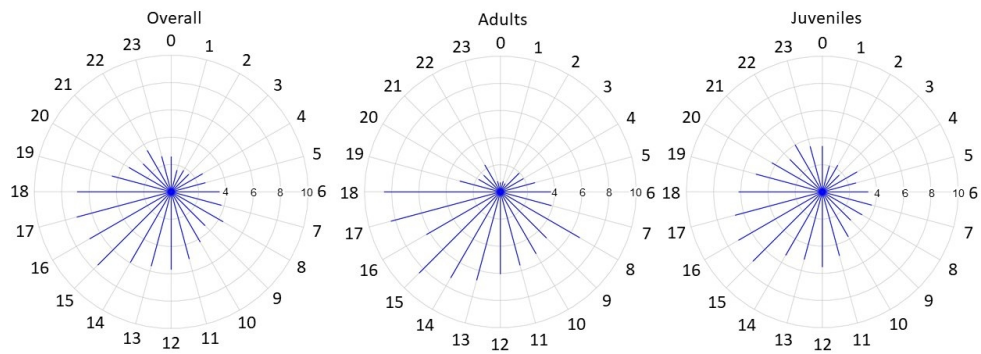
Original current u and v components (yellow dashed lines) and after clockwise rotation 117° relative to north (white lines). Arrows on the white lines show the direction of longshore u (LS U-ve and LS U+ve) and cross-shore v (CS V-ve and CS V+ve). Showing mooring locations: long thermistor string (red dot) and subsurface ADCP moorings (yellow dot).

27x25mm (600 x 600 DPI)



Percentage of detections at each site.

34x22mm (600 x 600 DPI)



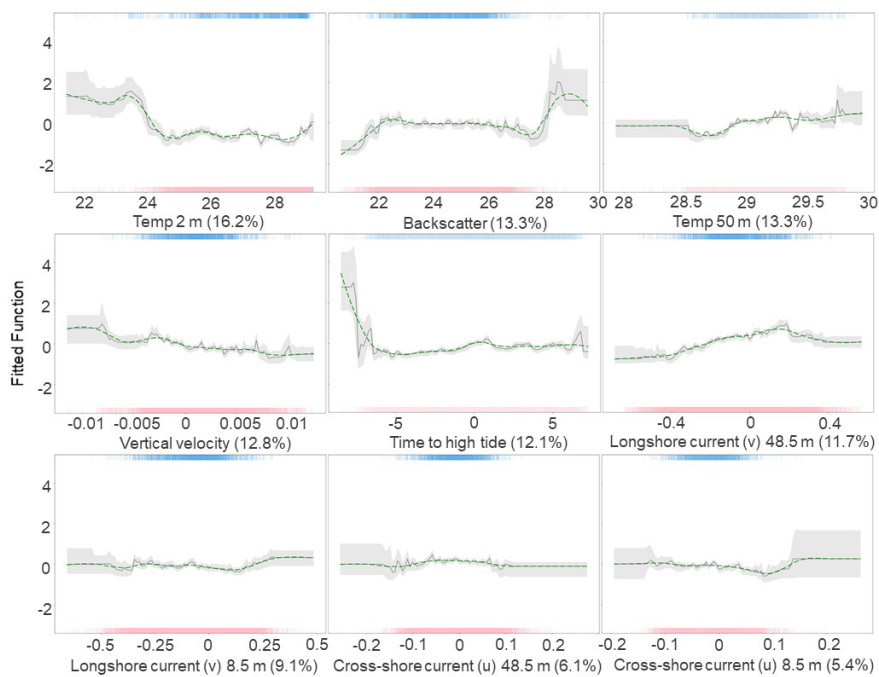
Percentage distribution of detections by hour of the day at Egmont Atoll for all tagged *M. alfredi* (left), adults only (middle) and juveniles only (right).

108x48mm (300 x 300 DPI)



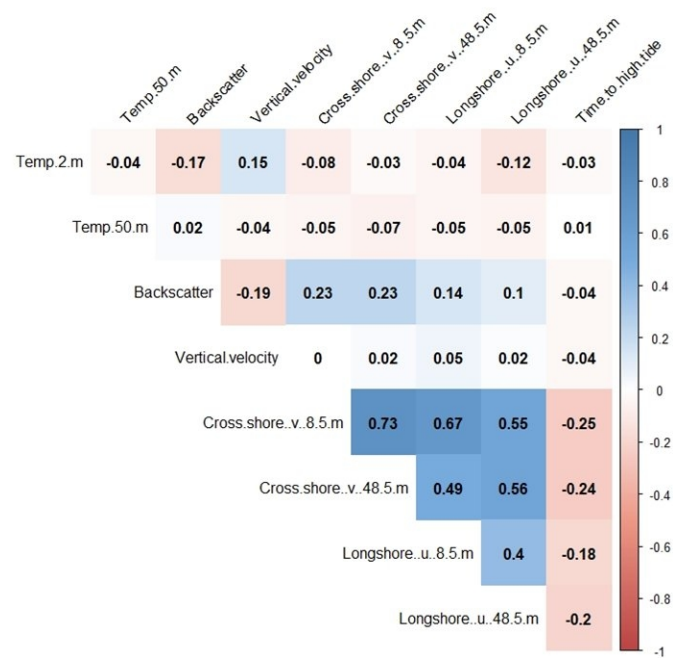
Resident events at each site showing location (by colour) and time at the location (by size).

40x22mm (600 x 600 DPI)



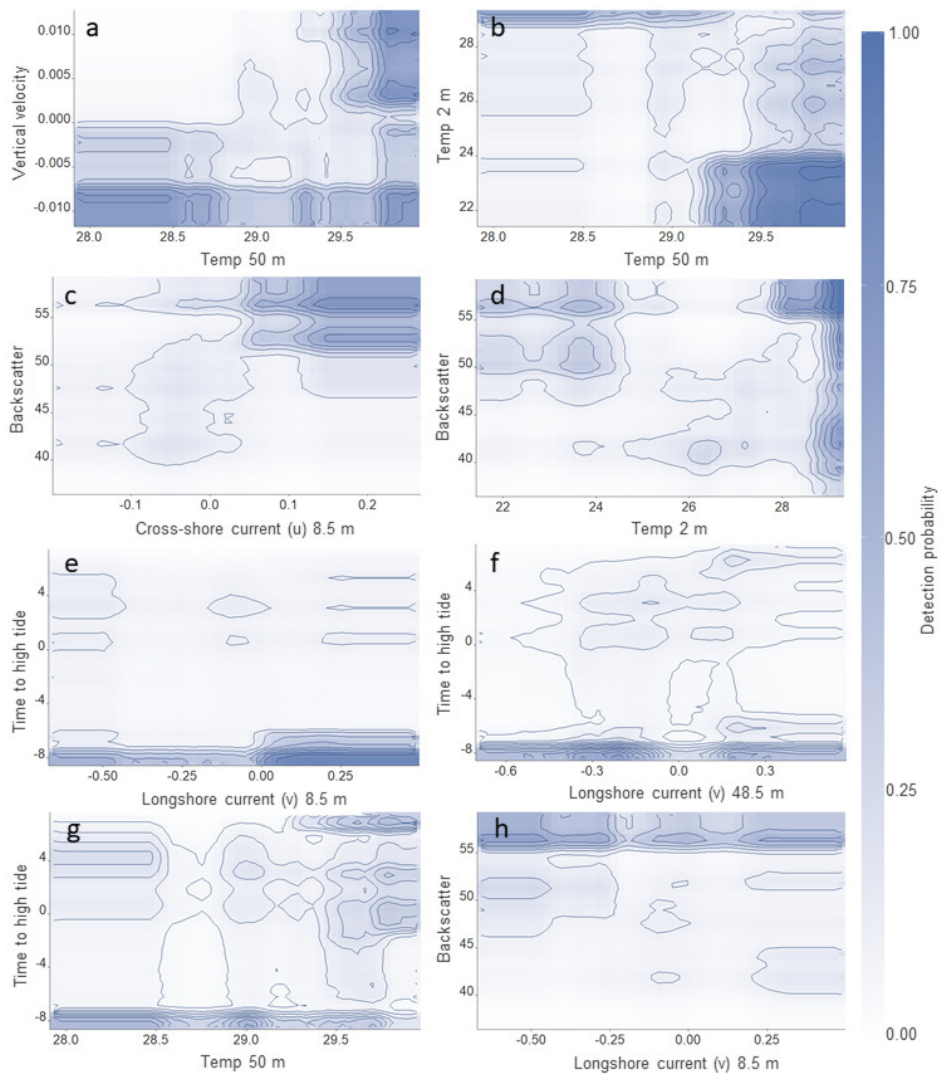
Partial dependency plots showing the effect of each predictor variable: temperature 2 m above the bed (Temp 2 m), depth-mean backscatter intensity linearly (Backscatter), temperature 50 m above the bed (Temp 50 m), upward (+ve) and downward (-ve) current flow (Vertical velocity), time relative to high tide in steps of 5-min (0.083h) with high tide zero, negative values before (flood) and positive values after (ebb) (Time to high tide), near-surface current 48.5 m above the bed (depth 17.6 m) flowing 117° (-ve) and 297° (+ve) relative to N (Longshore (u) 48.5 m), near bed current 8.5 m above the bed (depth 57.6 m) flowing 117° (-ve) and 297° (+ve) relative to N (Longshore (u) 8.5 m), near-surface current 48.5 m above the bed (depth 17.6 m) flowing 27° (-ve) and 207° (+ve) relative to N (Cross-shore (v) 48.5 m), near bed current 8.5 m above the bed (depth 57.6 m) flowing 27° (-ve) and 207° (+ve) relative to N (Cross-shore (v) 8.5 m), on the occurrence of tagged *M. alfredi* at Manta Alley while keeping all other variables at their mean. The green line shows smoothed partial dependency. Rugs display the distribution of the data for presence (top, blue), and absence (red, bottom).

99x67mm (300 x 300 DPI)



Correlation matrix for all predictors used in the boosted regression trees model.

88x60mm (300 x 300 DPI)



Pairwise interactions between predictor variables contour lines highlight the probability of *M. alfredi* tag detection at Manta Alley while keeping all other variables at their mean. All interactions were significant ($p<0.01$). Plot number related to the interaction effect shown in Table 3. A detailed description of each variable can be found in Table 1.

67x73mm (300 x 300 DPI)