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# Internal tides near the Celtic Sea shelf break: a new look at a well known problem

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## Abstract

Internal waves generated by tides in the Celtic Sea were investigated on the basis of in-situ data collected at the continental slope in July 2012, and theoretically using a weakly nonlinear theory and the Massachusetts Institute of Technology general circulation model. It was found that internal solitary waves generated over the shelf break and propagated seaward did not survive in the course of their evolution. Due to the large bottom steepness they disintegrated locally over the continental slope radiating several wave systems seaward and transforming their energy to higher baroclinic modes. In the open part of the sea, i.e. 120 km away from the shelf break, internal waves were generated by a baroclinic tidal beam which was radiated from the shelf break downward to the abyss. After reflection from the bottom it returned back to the surface where it hit the seasonal pychocline and generated packets of high-mode internal solitary waves. Another effect that had strong implications for the wave dynamics was internal wave reflection from sharp changes of vertical fluid stratification in the main pycnocline. A large proportion of the tidal beam energy that propagated downward did not reach the bottom but reflected upward from the layered pycnocline and

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returned back to the surface seasonal pychocline where it generated some extra higher mode internal wave systems, including internal wave breathers. *Key words:* Baroclinic tides, internal solitary waves, the Celtic Sea

# 1 1. Introduction and motivation

The Celtic Sea (CS) shelf break is one of the "hot spots" of the global 2 ocean where barotropic tidal energy is converted into a baroclinic compo-3 nent (Baines, 1982) making a great contribution to the sustainability of the 4 meridional overturning circulation. This is the reason why much attention 5 is focussed on this site with the aim of quantifying baroclinic processes that 6 develop there. The earliest works by Pingree and Mardell (1981, 1985) fol-7 lowed by more recent studies (Pingree and New, 1995; Holt and Thorpe, 1997; 8 Huthnance et al., 2001; Hopkins et al., 2012) reported the characteristics of 9 internal waves generated by tides over the Celtic Sea shelf break. 10

The most recent observations were conducted on the 376-th cruise of the RRS "Discovery" (hereafter D376) in June 2012 in the slope-shelf area. The task of the cruise was to quantify the cross shelf transport on the NE Atlantic Ocean margin. In doing so, several long-term moorings with thermistor chains and ADCPs were deployed in the area (some of them are shown in Fig.1), accompanied by CTD surveys and glider missions.

The data collected in-situ revealed evidence of a strong semi-diurnal baroclinic tidal signal that was accompanied by packets of short-period internal solitary waves with amplitudes up to 100 m. A detailed analysis of the characteristics of these waves, their spatial structure and dynamics was reported by Vlasenko et al. (2014) who replicated the generated wave fields numerically using the Massachusetts Institute of Technology general circulation model
(MITgcm). The model results were validated against the observational data
collected during the D376 cruise.

Two classes of tidally generated internal waves were identified in the area 25 with highly corrugated topography shown in Fig.1. Spiral-type internal waves 26 similar to those typical for isolated underwater banks were generated over the 27 headland. The other type was a system of quasi-planar internal wave packets 28 that were generated in the area of several canyons. The spatial structure of 29 these two wave systems is shown in Fig.1 a (see Vlasenko et al. (2014) for 30 more details). Note that the water stratification during the experiment was 31 characterised by a relatively sharp interface at the depth of 50 m and less 32 pronounced main pychocline located between 500 and 1200 metres (Fig.2 a). 33 Vlasenko et al. (2014) concluded that the strongest internal wave system 34

is a superposition of a 20 m amplitude semi-diurnal baroclinic tidal wave and a series of internal solitary waves (ISW). These waves were generated over the top of the headland (just in the place of the mooring ST2 deployed at isobath 185 m, see Fig.1 a) and radiated to the shelf and to the deep water towards mooring ST1. The isotherm time series, Fig.3 a, shows the vertical structure of the internal waves recorded at mooring ST1, and Fig.3 b represents a 5hour fragment with the strongest leading ISW of 105 m amplitude.

The normalized vertical profile of the largest ISW recorded at mooring ST1 is shown in Fig.3 c. It was built by calculation of the displacement of the chosen isotherm from its equilibrium depth before the ISW arrival and normalized by the wave amplitude. Fig.3 c shows that the wave profile reveals the properties of the second baroclinic mode that produces counter-phase

displacements of isotherms in the surface and bottom layers. To get a more 47 statistically justified result on the possible appearance of second-mode ISWs 48 at mooring ST1, another 45 of the largest ISWs, with amplitudes larger than 49 30 m, were analysed in a similar way. Considering the whole cluster of the 50 dots together it was expected to find a general tendency of their distribution 51 that is noise free and statistically significant. It is clear from Fig.3 d that all 52 ISWs are waves of depression in the surface 120 m layer. Below this depth 53 the dots are randomly distributed across the whole range between -1 and 1, 54 so that both the waves of depression and elevation were equally observed. 55

To make the point clearer, the eigenfunctions of the boundary value problem (BVP)

$$\frac{d^2\Phi}{dz^2} + \frac{N^2(z)}{c_i^2}\Phi = 0, \quad \Phi(0) = \Phi(-H) = 0.$$
(1)

were calculated. Here  $\Phi(z)$  is the vertical modal structure function,  $c_i$  is the phase speed of the *i*-th mode, N(z) is the buoyancy frequency shown in Fig.1 d, *H* is the water depth.

Two first eigenfunctions of the BVP (1) are presented in Fig.3 d. It is clear 61 that the vertical structure of the ISWs recorded at ST1 does not fit either the 62 first or the second baroclinic mode. However, initially at the place of their 63 generation (in the area of the mooring ST2, see Fig.1), the internal waves 64 had the structure of the first baroclinic mode (for the details see Vlasenko 65 et al. (2014)). Thus, it is unclear what happened to these waves on their 66 way from shallow mooring ST2 to the deeper ST1, i.e. in the course of their 67 seaward propagation (hereafter, "antishoaling"). What is the ultimate fate 68 of the waves generated on the CS slope: Do they dissipate locally or radiate 69 far away from the place of generation? These fundamental questions on the 70

mechanisms of the tidal energy conversion and its dissipation were a strong
motivation for the present study.

The paper is organized as follows. Section 2 describes the antishoaling process of ISWs in terms of a weakly nonlinear theory and using fineresolution modelling based on a 2D version of the MITgcm. Section 3 summarises the finding from the antishoaling study and formulates some further questions to be answered. Section 4 reports results of a high-resolution modelling of baroclinic tides in the area. Section 5 outlines the main findings.

# <sup>79</sup> 2. Does the antishoaling kills all ISWs?

#### 80 2.1. Weakly nonlinear analysis

Evolution of seaward propagating first mode ISW can be investigated in terms of the Gardner equation:

$$\frac{\partial \eta}{\partial t} + (\alpha \eta + \alpha_1 \eta^2) \frac{\partial \eta}{\partial x} + \beta \frac{\partial^3 \eta}{\partial x^3} = 0.$$
(2)

Here  $\eta$  is the displacement of the isopycnals; x is the spatial variable in the direction of wave propagation, and t is the time;  $\alpha$  and  $\alpha_1$  are the coefficients of quadratic and cubic non-linearities, respectively;  $\beta$  is the coefficient of dispersion. Note that  $\alpha$ ,  $\alpha_1$ , and  $\beta$  depend on the water depth and stratification as follows (Grimshaw et al., 1997):

$$\alpha = \frac{3c}{2} \frac{\int_{-H}^{0} \left(\frac{d\Phi}{dz}\right)^{3} dz}{\int_{-H}^{0} \left(\frac{d\Phi}{dz}\right)^{2} dz}, \quad \beta = \frac{c}{2} \frac{\int_{-H}^{0} \Phi^{2} dz}{\int_{-H}^{0} \left(\frac{d\Phi}{dz}\right)^{2} dz},$$
$$\alpha_{1} = \frac{3}{2c} \frac{\int_{-H}^{0} \left\{c^{2} \left[3\frac{dT}{dz} - 2\left(\frac{d\Phi}{dz}\right)^{2}\right] \left(\frac{d\Phi}{dz}\right)^{2} - \alpha^{2} \left(\frac{d\Phi}{dz}\right)^{2} + \alpha c \left[5 \left(\frac{d\Phi}{dz}\right)^{2} - 4\frac{dT}{dz}\right] \frac{d\Phi}{dz}\right\} dz}{\int_{-H}^{0} \left(\frac{d\Phi}{dz}\right)^{2} dz}$$

Here  $\Phi = \Phi_1$  and  $c = c_1$  are defined from the BVP (1), T is a normalized solution of the following boundary value problem

$$c\frac{d^2T}{dz^2} + N^2(z)T = -\alpha c\frac{d^2\Phi}{dz^2} + \frac{3c}{2}\frac{d}{dz}\left[\left(\frac{d\Phi}{dz}\right)^2\right],\tag{3}$$

$$T(0) = \overline{T}(-H) = 0,$$
 (4)

The steady state solutions of the Gardner equation (2) depend on the sign of the coefficients  $\alpha$  and  $\alpha_1$ . Fig.4 shows the dependence of the coefficients  $\alpha$ (red line) and  $\alpha_1$  (blue line) from depth H. It is clear that in the near-shore zone (shalower than 2 km) the coefficient of the quadratic nonlinearity  $\alpha$ changes its sign twice. The coefficient of the cubic nonlinearity  $\alpha_1$  is positive on the shelf but negative over the slope deeper than 1260 m.

In the shallow water zone where  $H \leq 850 \,\mathrm{m}$ ,  $\alpha < 0$  and  $\alpha_1 > 0$ , and 96 according to (Grimshaw et al., 1999, 2004) either negative algebraic solitons 97 or breathers are allowed. For the depth  $850 \,\mathrm{m} < H < 1270 \,\mathrm{m}$  both coefficients 98 are positive, and the weakly nonlinear theory predicts the existence of either 99 positive algebraic solitons or breathers. Moving further offshore to depths 100  $1270 \,\mathrm{m} < H < 1750 \,\mathrm{m}$  the coefficient of the cubic nonlinearity changes its 101 sign again, Fig.4, allowing only positive ISWs, whereas at deeper the isobath 102 1750 m only negative ISWs are expected. 103

The spatial variability of the coefficients  $\alpha$  and  $\alpha_1$  has strong implications for the dynamics of internal waves. It was found that ISWs generated at the shelf break in the area of the mooring ST1 are the waves of depression (Vlasenko et al., 2014). However, the weakly nonlinear theory predicts that after passing the turning point at H=850 m these waves have to change their polarity or transform into a breather. Probably the proximity of mooring

ST1 to the turning point is the reason why the vertical structure of ISWs 110 shown in Fig.3 a does not fit the structure of the first baroclinic mode. To 111 learn more about the wave dynamics in the area and to check whether a 112 dramatic transformation of ISWs propagated seaward as predicted by the 113 weakly nonlinear theory is correct, a series of numerical experiments on the 114 antishoaling of ISWs was conducted. We restrict our interests to a 2D-115 version of the problem in order to have a fine resolution grid that allows a 116 more accurate reproduction of the cross-slope wave transformation. 117

#### 118 2.2. Numerical modelling

In numerical experiments with seaward propagating ISWs the vertical 119 and horizontal grid steps were  $\Delta z=10$  m and  $\Delta x=7.5$  m, respectively, and 120 the buoyancy frequency was set as that shown in Fig.2 a by the thin line. 121 The bottom profile was defined along the cross-section depicted in Fig.1. 122 Initial fields for this series of model runs were prepared as it was done in 123 Vlasenko et al. (2009). An 80 m amplitude first-mode K-dV ISW of depres-124 sion propagating in a basin of 200 m depth was used for the model initial-125 ization. Being inserted into the numerical scheme it started to evolve due to 126 strong nonlinearity into a new solitary wave. This new-born stationary 53 m 127 amplitude "numerical" ISW was used afterwards as an initial condition in 128 the experiments on antishoaling. 129

Seaward propagation of ISW is presented in Fig.5. Here the horizontal and vertical velocity fields overlaid with the temperature field at different stages of the wave evolution are shown in the middle and bottom panels, respectively. In order to have a guess whether the propagated ISW can be visible on syntetic aperture radars (SAR) images, the top panel represents the wave-induced horizontal velocity gradient du/dx at free surface z = 0. According to Alpers (1985) the radar recognises ISWs as systems of bright and dark bands if the wave signal du/dx(z=0) is of the order of  $10^{-3}$  s<sup>-1</sup>.

Analysis of Fig.5 shows that in the shelf break area where the water depth 138 is less than 850 m, the ISW behaves as the weakly nonlinear theory predicts, 139 i.e. in the course of evolution a negative ISW adjusts its structure adia-140 batically to the varying topography. After passing the turning point where 141 the quadratic nonlinearity changes its sign (see Fig.4), the ISW starts to 142 transform, but not exactly as the weakly nonlinear theory predicts. Instead 143 of changing its polarity in the whole water column the wave turns into a 144 second-mode ISW. As a confirmation of that, in the deep part of the basin 145 where the depth exceeds 1100 m the horizontal velocity changes its sign twice 146 from the surface to the bottom revealing properties of the second mode (the 147 most right panel in Fig.5 b). This conclusion is also confirmed by the coun-148 terphase displacements of the isotherms in the surface and bottom layers, 149 and by the spatial structure of the vertical velocity shown in Fig.5 c. 150

The process of energy conversion from lower to higher modes continues 151 to progress in the course of the wave evolution. Being a second-mode wave 152 at the 1700 m isobath (its structure is shown in two left panels in Fig.6), 153 the seaward propagated ISW transforms into a packet of third-mode internal 154 waves at a depth of 4000 m (two right panels in Fig.6). Thus, it is clear from 155 the comparison of the weakly-nonlinear theory predictions and the fully-156 nonlinear model output that the theory correctly predicts the positions of 157 the turning points, but fails to describe disintegration of ISWs into packets 158 of higher modes. 150

One of the possible reasons for such unexpected transformation of the 160 propagated ISWs could be inapplicability of the weakly non-linear theory 161 over the continental slope. In fact, the Gardner equation (2) is valid for 162 shallow water systems when  $\lambda/H \gg 1$  ( $\lambda$  is the wave length and H is water 163 depth). The horizontal scale of the initial 53 m ISW on the 200 m depth shelf 164 is about 1.5 km (i.e.  $\lambda \approx 750$  m), so formally this ISW can be classified as a 165 long wave. However, over the continental slope and in the open part of the 166 sea this condition is not valid. To check whether the ratio of the wavelength 167 to the water depth is a key parameter controlling the wave evolution (and 168 applicability of the shallow water theory), another experiment with a 2 m am-169 plitude (and three times longer wavelength) ISW was conducted. However, 170 it was found that, similar to the large amplitude ISWs, the 2m amplitude 171 ISW also reveals strong energy transfer from the first to highest modes in 172 the course of its evolution (not shown here). In fact, the sensitivity runs 173 have confirmed that the energy transfer to the higher modes over an inclined 174 bottom does not depend on the amplitude/wavelength ratio. 175

Another reason for the cross-mode energy transport could be the steep-176 ness of the bottom topography. It is equal to 0.13 (or  $7.5^{\circ}$ ) between the 600 177 and 1000 m isobaths. In situations when the wave crosses strong horizontal 178 gradients, the transfer of wave energy to higher modes is quite possible. In 179 order to check whether this is the case, some extra numerical experiments 180 were conducted. In a new series of model runs all settings were the same as 181 above except for the bottom steepness which was reduced to 0.01 (i.e.  $0.6^{\circ}$ ). 182 Three fragments of the wave antishoaling over the flat topography are 183 shown in Fig.7. The spatial structure of the horizontal velocity reveals the 184

properties of the first mode at all stages of wave evolution. There is still evidence of the energy leak to the second and third modes in the wave tail (find the wave fragment between 55 and 70 km), but this fragment accounts for only 3% of the total energy of the initial ISW.

Thus, this experiment has confirmed that steep topography is the main 189 reason for the energy transfer from the first mode ISW to the higher modes. 190 Presumably, evidence of such a transformation was recorded at the deep 191 mooring ST1, Fig.3d. Note also that collapse of the seaward propagated 192 ISW over steep topography was accompanied by a radiation of several wave 193 systems overtaking the main wave packet. The process of wave radiation is 194 clearly seen in the Hovmöller diagram presented in Fig.8 a. Here the instant 19 profiles of the free surface velocity are shown for 45 hours of wave evolution. 196

Fig.8 a shows that an internal wave train is radiated forward after the ISW passes the 850 m isobath. In the Hovmöller diagram this wave system is marked by the arrow with number 1. In the deep part of the ocean this packet has amplitude less than 10 m, and propagates here with velocity  $2.38 \text{ m s}^{-1}$ , which is close to the value  $2.45 \text{ m s}^{-1}$  predicted by BVP (1) for the first baroclinic mode (the blue line in Fig.8 b). Vertically the structure of this leading wave system (not shown here) resembles first baroclinic mode.

A few hours later when the wave system passes the 1800 m isobath a second wave packet detaches from the main wave train and overtakes it (find arrow 2 in Fig.8 a,). An average propagation speed of the new born packet is equal to  $1.08 \text{ m s}^{-1}$ , which almost ideally coincides with the second eigenvalue of the BVP (1),  $1.10 \text{ m s}^{-1}$ .

209

It is interesting that the phase speed of the strongest wave fragment over

the slope (find arrow 4 in Fig.8 a) remains constant, viz.  $0.42 \,\mathrm{m\,s^{-1}}$ , during four days of evolution. At the beginning of the ISW antishoaling this velocity was equal to the phase speed of the first baroclinic mode on the shelf (dotted line in Fig.8 b). At the latest stages of ISW evolution, i.e. in the deep water part of the basin, this value is close to the phase speed of the fourth baroclinic mode. Evidence of higher baroclinic modes can be seen in vertical structure of the horizontal and vertical velocity fields shown Figs.6 e and 6 f.

## 217 3. T-beam generation of ISWs in the far field

It was shown above that the ISWs generated over the shelf break and 218 propagated seaward disintegrate into packets of the first, second, and higher 219 baroclinic modes losing a large proportion of their initial energy. As a result, 220 the surface signal du/dx(z=0) of propagated 53 m amplitude ISW drops 221 from initial  $1.5 \cdot 10^{-3} \text{ s}^{-1}$  on the shelf to  $0.03 \cdot 10^{-3} \text{ s}^{-1}$  in the deep part (see 222 Figs.5 a and 6 d). Therefore, it is unlikely that propagated seaward ISWs can 223 be observed far from the shelf break. Note, however, that the remote sensing 224 data presented by New and Da Silva (2002) for the Bay of Biscay (BB) 225 (45-48°N, 5-9°W, Fig.1), clearly show evidence of ISWs at a distance of 120-226 150 km (hereafter the "far field"), see Fig.1 b. Scrutiny of the ISW signature 227 pattern also shows that there is no strong evidence of ISWs between the shelf 228 break area (hereafter "near field") and the far field. Only a few wave systems 229 are presented there. 230

New and Pingree (1990, 1992) and Pingree and New (1989, 1991) explained the appearance of internal waves in the far field in terms of local generation. In short, this mechanism suggests that the tidal internal waves generated over a supercritical topography are radiated from the shelf break
to the abyss in the form of a tidal beam (hereafter "T-beam") along one of
the characteristics lines

$$\int \frac{dz}{\gamma(z)} = \pm x + \text{const}, \quad \gamma(z) = \sqrt{(\sigma^2 - f^2)/(N^2(z) - \sigma^2)}, \tag{5}$$

<sup>237</sup> of the hyperbolic wave equation:

$$w_{xx} - \gamma^2(z)w_{zz} = 0.$$
 (6)

Here w is the vertical velocity,  $\sigma$  is the M<sub>2</sub> tidal frequency, f is the Coriolis parameter. After reflection from the bottom the T-beam returns to the surface 120 km away from the shelf break where it hits the pycnocline and generates internal waves. Gerkema (2001) confirmed the possibility of this mechanism for the BB theoretically using simplified stratification with mixed surface layer and two underlying layers with constant stratification. Schematically, the idea of the T-beam generation is presented in Fig.1 c.

Note that considered here area is next to the BB, Fig.1. As such two basins should have similar conditions for internal wave generation, viz. fluid stratification, bottom profiles, and tidal forcing. If so, a similar appearance of ISWs in the far field of two basins is expected. To investigate the local generation of ISWs by a T-beam in the far field a two-dimensional version of the fully nonlinear nonhydrostatic MITgcm was applied.

The model domain was chosen to be long enough to reproduce the internal waves in the far field. The bottom profile was similar to those used in the experiments with ISW antishoaling, Fig.1. The spatial resolution was  $\Delta x=15$  m and  $\Delta z=10$  m. The tidal forcing was defined using the ADCP measurements for the period of 25-27 June 2012 (days 177-179 of 2012) when the strongest ISWs were recorded at mooring ST1, Fig.3. The amplitude of tidal discharge in northern and eastern directions was equal to  $60 \text{ m}^2 \text{ s}^{-1}$ . The background vertical viscosity and diffusivity coefficients were taken at a minimum level, i.e.  $10^{-5} \text{ m}^2 \text{s}^{-1}$ , but with the Richardson number parametrization for extra mixing in the areas with hydrodynamic instabilities produced by internal waves. The coefficients of horizontal viscosity and diffusivity were set constant,  $0.1 \text{ m}^2 \text{s}^{-1}$ .

Two buoyancy frequency profiles, (i) a smoothed climatic one based on the Boyer et al. (2009) data set, and (ii) an instant profile taken from the D376 yo-yo CTD cast to 1200 m depth extended by the climatic data below 1200 m, were used in modelling. These two profiles are shown in Fig.2 a by the thick and thin lines, respectively. The difference between the model outputs obtained for both cases is discussed below.

#### 269 3.1. Smoothed stratification

The dynamics of internal waves can be studied using the Hovmöller di-270 agram, Fig.9a. It shows the evolution of vertical displacement (left axes) 271 of the 13°C isotherm during the time span 240-252 h (right axes) after the 272 beginning of the experiment. Fig.9 b represents the amplitude of the hori-273 zontal velocity during the 21-st tidal cycle. A long term spin-up of the model 274 was required to allow higher baroclinic tidal modes to propagate through the 275 whole model domain. Their superposition results in the formation of a tidal 276 beam that is clearly seen in both the near and far fields, Fig.9b. 277

The T-beam is quite a narrow band with a high intensity of baroclinic tidal energy. It starts at point (a) on the shelf edge and propagates downward to the abyss along the characteristic line (5) that is depicted in Fig.9 b by the dashed white contours. After reflection from the bottom at point (b) the baroclinic tidal energy returns back to the surface at point (c).

In the shelf break area (between 10 and 20 km) Fig.9 a shows evolution 283 of two systems of short waves generated over the shelf break. The first 284 group comprises two wave packets (1)-(2)-(3) highlighted by yellow colour. 285 It seems that both packets, one directed to the shelf and another to the open 286 sea, were generated according to the lee wave mechanism. The other wave 287 system shown in orange (fragments (4)-(7)) was developed due to steepening 288 and disintegration of propagating internal tidal wave (Vlasenko et al., 2005). 289 Both systems remain visible during one additional tidal cycle and attenuated 290 in the deep part of the sea according to the mechanism of disintegration 291 discussed in Section 2. 292

On the other side of the model domain, i.e. in the far field, the wave motions are also well developed. The strongest wave system (8)-(9) (in Fig.9 a it is marked by blue colour) starts to develop at point (c) where the tidal beam hits the pycnocline located just below the free surface (at 50 m depth, see Fig.2 a). At the first stage the generated wave looks like a bore propagated seaward. It becomes steeper in the course of nonlinear evolution gradually transforming into a packet of rank-ordered ISWs.

The propagation speed of the wave fragment (8)-(9) calculated on the basis of the Hovmöller diagram, Fig.9 a, is equal to  $0.61 \,\mathrm{m \, s^{-1}}$ , which is well below the phase speed of the first mode ISWs, but close to the velocity of the third mode (first four eigenvalues of the BVP (1) for the depth 4.3 km are equal to 2.52, 1.23, 0.68, and  $0.45 \,\mathrm{m s^{-1}}$ , respectively). Thus, the slow velocity of propagation suggests that specific features of the high baroclinic

modes should be evident in the vertical stucture of the wave packet (8)-(9). 306 Fig.10 represents the displacements of isotherms and the vertical velocity 307 of the wave packet depicted in right bottom corner of Fig.9 a by a magenta 308 rectangle. It is clear from Fig.10 a that the leading wave in this packet is the 309 wave of depression in the surface 200 m layer (maximum displacements up to 310  $35 \,\mathrm{m}$ ), but it is the wave of elevation between  $800 \,\mathrm{m}$  and  $1100 \,\mathrm{m}$  depths. The 311 high mode wave structure is more evident in Fig.10 b which shows that the 312 vertical velocity changes its sign twice along the dashed line in panel Fig.9 b, 313 which is a specific feature of the third mode. 314

One can also identify in Fig.9 b a secondary tidal beam originated at point (d) located in the layer of the main pycnocline, i.e. around 900 m depth, see Fig.2 a. This beam propagates to the surface along the characteristic line, where it is reflected from the surface downward at point (e), and ultimately ends up at the bottom at point (f). The explanation of this phenomenon can be found in terms of the mechanism of scattering of the main tidal beam from layers with a sharp change of vertical stratification discussed below.

# 322 3.2. D376 buoyancy frequency profile

The buoyancy frequency profile recorded during cruise D376 was used in 323 the next series of numerical experiments. As seen from Fig.2a, the instant 324 profile (shown by the thin line) is highly corrugated in the layer of the main 325 pycnocline, specifically between 750 m and 1200 m depths. High intermit-326 tency of vertical fluid stratification creates favourable conditions for internal 327 wave reflection from layered fluid structures. The effect of tidal beam re-328 flection from a pychocline was reproduced numerically by Gerkema (2002) 329 and proven in laboratory experiments by Wunsch and Brandt (2012). There 330

are only a few specific profiles of the buoyancy frequency (see (Magaard,
1962; Vlasenko, 1987)) that allow internal wave propagation without reflection. Sharp increase or decrease of the vertical density gradients can lead to
a massive reflection of the tidal beam energy (Grimshaw et al., 2010)

The T-beam energy reflection from the layers with sharp changes of buoy-335 ancy frequency is illustrated in Fig.11. The intermittent layered structure of 336 the main pycnocline between 750 m and 1200 m depths resulted in a stronger 337 secondary tidal beam (d)-(e), Fig.11b, than it was for the smoothed pro-338 file, Fig.9 b. Moreover, an additional tidal beam, viz. (g)-(h), has appeared 339 in Fig.11b. It was generated by reflection of the tidal energy of the main 340 beam (a)-(b) from a number of layers of intermittent stratification in the 341 main pychocline. As a consequence of this strong internal energy reflection, 342 the main tidal beam (a)-(b) below 1500 m is much weaker in Fig.11 b than 343 it was in Fig.9b. In other words, a large part of the beam energy returns 344 to the surface in the area between the far- and near fields. In this area the 345 secondary tidal beams (d)-(e) and (g)-(h) interact with the subsurface pyc-346 nocline and generate locally two new wave systems depicted in Fig.11 a by 347 numbers (1)-(2) and (3)-(4). 348

The intensity of the signals produced by wave systems (1)-(2) and (3)-(4) at the free surface is strong enough to be visible from space by SARs. The derivative du/dx(z = 0) of the model output at t = 252 h is shown in Fig.12 a. Note, however, that the spatial and temporal characteristics of these wave two systems are quite different. The speed of propagation of the wave packet (1)-(2) is equal to  $0.61 \text{ m s}^{-1}$ , which coincides with the phase speed of the ISW packets (6)-(7) and (8)-(9) shown in Fig.9 a. Moreover, spatially all these wave packets are mostly rank-ordered (see, for instance, Fig.12 b)
resembling a third baroclinic mode in the vertical direction, Fig.12 d.

Wave system (3)-(4) is quite different from packet (1)-(2). It propagates 358 much slower, i.e. with average speed  $0.17 \,\mathrm{m\,s^{-1}}$  (see Fig.11a). Further 359 analysis of its spatial structure has shown that the wave system (3)-(4) can 360 be classified as an internal wave breather (Lamb et al., 2007), i.e. a localised 361 wave packet with a sinusoidal periodic carrier that is restricted in space by a 362 soliton-shape envelope, as shown Fig.12 c. Weakly nonlinear theory predicts 363 such quasi-stationary solutions, internal breathers, that remain stable in the 364 course of their propagation. Fig.11 a shows that wave packet (3)-(4) does 365 keep its form at least one and a half tidal period until it was overtaken by 366 another wave group. 367

In fact, the phase speed of the carrier wave should not necessarily coincide 368 with the propagation velocity of the breather, i.e. the group speed. For the 369 surface wave in deep water, for instance, the phase speed of the breather's 370 carrier is double as high as the group speed (Zakharov, 1968; Slunyaev and 371 Shrira, 2013). In the present case the phase speed of the carrier is equal to 372  $0.30 \,\mathrm{m\,s^{-1}}$ , which is almost twice as high as the breather's speed. This value 373 was calculated using the frequency of the carrier wave  $0.0025 \text{ s}^{-1}$  (found from 374 the model by sampling at several fixed points that the breather crosses) and 375 an average wavelength 660 m of the wave carrier detected from Fig.11 (see 376 also Fig.12). 37

It is interesting to validate the model-predicted parameters of the breather against some theoretical values obtained from the boundary value problem:

$$\frac{d^2\Phi_j}{dz^2} + \frac{k_j^2}{\gamma^2(z)}\Phi_j = 0, \quad \Phi_j(0) = \Phi_j(-H) = 0.$$
(7)

Here  $\Phi_j(z)$  is the vertical structure function and  $k_j$  is the wave number of 380 the *j*-th mode. As distinct from (1), BVP (7) calculates wave numbers and 381 vertical structure of periodic internal waves. The dispersion relations of the 382 first three baroclinic modes are shown in Fig.13. For the wave carrier with 383 frequency  $0.0025 \text{ s}^{-1}$  and the fluid stratification shown in Fig.2 a the wave 384 length, phase speed, and the group speed of the first three modes (j=1,2,3)385 are shown in the Table. The model-predicted parameters of the numerical 386 breather carrier from the Hovmöller diagram, Fig.11a, are as follows: the 387 wavelength - 600 m, phase speed -  $0.30 \,\mathrm{m\,s^{-1}}$ , and group velocity  $0.17 \,\mathrm{m\,s^{-1}}$ . 388 It is clear from the Table that the third baroclinic mode provides the best fit 389 to the model predicted parameters of the numerical breather carrier wave. 390 This is also consistent with Fig.12e, that shows the vertical structure of the 391 breather. 392

New and Da Silva (2002) analysed parameters of more that 100 ISWs 393 observed in SAR images of the BB (see Fig.1b), which is next to the con-394 sidered here area. This data set can be taken as indirect validation of the 395 model output. It was found that the wavelengths of the whole ensemble of 396 observed ISWs ranged from 0.6 to 3.0 km, with a mean value of 1.35 km. 397 The wavelengths  $\lambda_1, \lambda_2, \lambda_3$  shown in Fig.12 b are 1.35, 1.15, and 0.85 km, re-398 spectively, that is in agreement with the observations by New and Da Silva 399 (2002). It is also interesting that 10% of all reported ISWs were quite short. 400 They had their wavelengths in the range between 600 and 800 m which is 401 consistent with the wavelength  $\lambda_4 = \lambda_5 = 660 \text{ m}$  of the internal breather shown 402 in Fig.12 c. 403

#### 404 4. Discussion and conclusions

The present study was motivated by the fact that majority of ISWs 405 recorded at the mooring deployed on the continental slope of the Celtic Sea 406 in July 2012 exhibited properties of the second baroclinic mode. In light of 407 the most recent modelling efforts by Vlasenko et al. (2014) who reproduced 408 numerically the three-dimensional dynamics of the baroclinic tides in the 409 area and showed that first-mode ISWs are generated over the shelf break, 410 this observational evidence of higher baroclinic modes over the continental 411 slope required further scrutiny. 412

A preliminary analysis of the wave dynamics in terms of a weakly nonlin-413 ear theory has shown that all ISWs generated over the shelf break and prop-414 agated seaward over an inclined bottom must change their form after passing 415 the turning points, i.e. the isobath where the coefficients of the quadratic 416 and cubic nonlinearities of the Gardner equation (2) change their sign. This 417 non-adiabatic behaviour of ISWs was reproduced numerically using the fully 418 nonlinear nonhydrostatic MITgcm. The numerical runs convincingly showed 419 that steepness of the bottom topography is the major factor controlling the 420 process of wave disintegration. It was found, however, that the seaward prop-421 agated ISWs do not evolve exactly as the weakly non-linear theory predicts. 422 Quite opposite, after passing the turning point where the coefficient of the 423 quadratic nonlinearity  $\alpha = 0$ , the ISW did not change its polarity but started 424 to transfer its energy to higher modes. This process was accompanied by 425 forward radiation of low-mode internal wave systems. The first-mode wave 426 packet is radiated first, then the second mode, etc, as shown in Fig.8. 427

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It was found that the reason for the energy transfer to higher modes is the

steep gradient of the continental slope. Sensitivity runs with much smaller
bottom inclinations have shown that ISW really reverses its polarity after
passing the turning point according to a classical mechanism predicted by
the weakly nonlinear theory.

Overall, the seaward propagated ISWs do not escape far from the shelf 433 break and cannot be observed on SAR images far away from the shelf break. 434 Figs.6 a and 6 d clearly show that in the open part of the sea the surface 435 signal produced by seaward propagated ISWs is much weaker than  $10 \, \mathrm{s}^{-3}$ 436 which is considered as a threshold for detection of ISWs by SARs (Alpers, 437 1985). Note, however that these high-mode waves, being invisible from space, 438 are still able to form strong circulation cells at the depths of 1000-1500 m 430 (see Figs.6 b-c and 6 e-f). Ultimate disintegration and wave breaking can 440 lead to strong local water mixing and formation of the intermittent layered 441 stratification of the main pycnocline shown in Figs.2 b-e (Boyer et al., 2009). 442 The appearance of internal waves in the far field is explained here in 443 terms of the spatial structure of baroclinic tides. A tidal beam is generated 444 over supercritical topography and propagates downward from the shelf break 445 to the abyss along the characteristic line  $\int 1/\gamma(z)dz = x + \text{const}$  of the 446 hyperbolic wave equation (5). After reflection from the bottom the tidal 447 beam returns to the free surface in the far field where it hits the pycnocline 448 and generates internal waves. 449

The MITgcm reproduced the tidal beam over the shelf break of the Celtic Sea quite accurately. The model predicted wave velocities inside the tidal beam (up to  $16 \,\mathrm{cm \, s^{-1}}$  during the spring tide) and its spatial position were consistent with that recorded at the deep water mooring deployed in the BB <sup>454</sup> 58 km from the shelf break (Pingree and New, 1991). The new element found
<sup>455</sup> in the present study concerns the vertical structure of the ISWs in the far
<sup>456</sup> field. The model reproduced third-mode ISW packets generated locally. An
<sup>457</sup> example of such a wave packet is shown in Fig.12.

It should be noted here that Grisouard and Staquet (2010) in their nu-458 merical analysis of the T-beam generation of internal waves in the BB also 459 reproduced the second mode in the far field (their Figs.2 and 3). It is in-460 teresting that in the earliest publications by New and Pingree (1990, 1992). 461 and in a more recent interpretational paper by New and Pingree (2000) the 462 observed in the BB ISWs were treated as the first-mode waves. Unfortu-463 nately, it is not possible to confirm or disprove this fact from the provided 464 observational data that cover only a surface 150 m layer. The temperature 465 time series presented in Fig.3 a also shows all ISWs as waves of depression 466 near the surface, but they clearly reveal properties of higher modes in the 467 deep, Fig.3d. 468

An indirect confirmation of the modal structure of ISWs can be deduced 469 from their phase speed calculated based on SAR images. New and Da Silva 470 (2002) analysed satellite images assuming the first-mode phase speed of the 471 observed waves which is close to  $1 \,\mathrm{m\,s^{-1}}$ . However, Envisat-ASAR image 472 from the middle of the BB dated 12 August 2005 and published in (Muacho 473 et al., 2014) (their Figure 2) allows one to calculate this value very accurately. 474 The image presented in Fig.14 clearly shows at least nine circular wave fronts 475 with an average distance between them of about 25 km. Assuming a semidi-476 urnal tidal periodicity of the observed waves it can be found that their phase 477 speed must be equal to  $0.55 \,\mathrm{m \, s^{-1}}$ , which is close to  $0.6 \,\mathrm{m \, s^{-1}}$ , i.e. the model 478

predicted phase speed found from Fig.11. It is interesting that Grisouard
and Staquet (2010) in their numerical experiment E2 also found that the two
wave trains were separated by 25-30 km, meaning that these ISWs propagate
at almost half of the speed estimated by New and Pingree (1990); New and
Da Silva (2002).

A series of sensitivity runs with smoothed and realistically intermittent 484 fluid stratification has shown that sharp changes of the vertical fluid stratifi-485 cation are the sites of internal wave reflection. As a result of strong internal 486 wave reflection from a layered main pychocline quite a substantial part of 487 the T-beam energy propagated from the shelf break downward to the abyss 488 returns to the surface in the area between the near- and the far fields where 489 it generates locally some extra internal wave systems. Numerical evidence of 490 this effect is shown in Fig.11. This could be a reasonable explanation of why 491 ISW packets are still visible in SAR images between the near- and far fields. 492 Note also that the backward reflection of the T-beam from the layers 493 with intermittent stratification was conducted here for a relatively smoothed 494 stratification (see Fig.2 a) that was found by averaging of 14 instant buoyancy 495 frequency profiles recorded in D376 cruise at the yo-yo CTD station. The 496 effect of T-beam reflection can be even stronger in case of real instant profiles 497 that are much more "fuzzy", Figs.2 b-e. Four of them acquired from Boyer 498 et al. (2009) are shown in Fig.2 b-e. They reveal very strong local layering 490 between 500 m and 2000 m depths that can provide much stronger T-beam 500 reflection. 501

Another finding from the present study is shown in Figs.12 c and e. Analysis of all characteristics of this wave system generated by the secondary tidal

beam, Fig.11, has shown that this wave packet can be classified as an internal 504 wave breather. First of all, it is not rank-ordered; maximal amplitudes are 505 located in the middle of the packet. It was found that this wave system prop-506 agates as a periodic wave train with a soliton envelope. Most importantly, 507 this form is stable in space and time (see Fig.11, wave (3)-(4)). Secondly, this 508 packet propagates much slower than the rank-ordered wave packets. More-509 over, the group speed of this packet is twice as small as the phase speed of 510 the carrier wave. Theory-wise, all these characteristics are associated with 511 internal wave breathers that are probably generated in the far field, but some 512 further research is required. 513

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Mode	Wavelength (m)	Phase speed $(m s^{-1})$	Group speed $(m s^{-1})$
1	2346	0.93	0.27
2	890	0.35	0.21
3	675	0.27	0.13

Table 1: Parameters of first three baroclinic modes

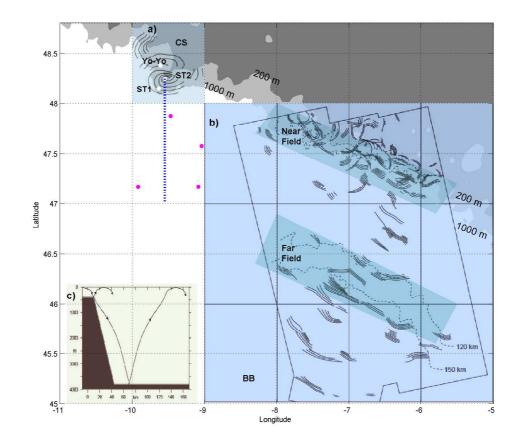


Figure 1: Shelf break of the Celtic Sea presented by the 200 m izobath. Positions of three moorings, Yo-Yo, ST1, and ST2 deployed during cruise D376 are depicted by black dots. Vertical dotted line shows the cross-section used in numerical modelling. a) Plan view of tidally generated internal wave systems predicted by the MITgcm (Vlasenko et al. (2014)). Time interval between two wave fronts equals 2 h. b) Composite image of all ISW packets observed in July 1994 and July-September 1999 in the Bay of Biscay and reported by New and Da Silva (2002). The observational area ranges from 5 to 9°W which is adjacent to the domain considered here. c) The tidal beam that is mentioned in the aforementioned paper as a reason for a local generation of internal waves in the far field.

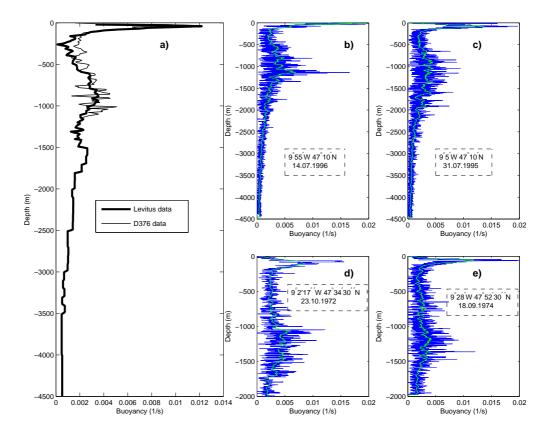


Figure 2: a) Vertical profiles of the buoyancy frequency: recorded at the Yo-Yo station (light line) and produced using the Levitus data set (thick line). Red lines depict the model profiles used in Section 3. b)-e) Buoyancy frequency profiles recorded at four CTD stations shown in Fig.1 by red dotes (Boyer et al., 2009).

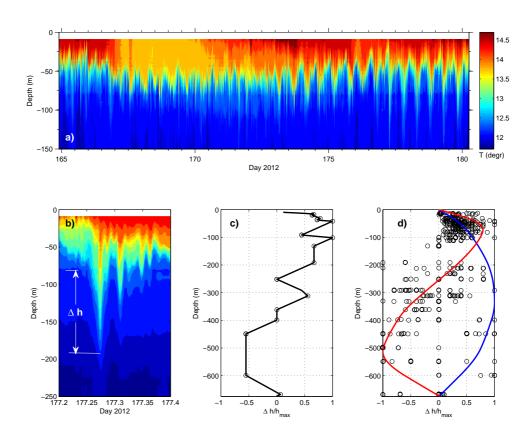


Figure 3: (a,b) Temperature recorded at mooring ST1. (c) Normalized vertical structure function of isotherm displacements of the leading ISW shown in panel (b). (d) The normalised wave displacements of the strongest 45 ISWs recorded at ST1. Blue and red lines show the normalized profiles  $\Phi_1$  and  $\Phi_2$  of the boundary value problem (1), respectively.

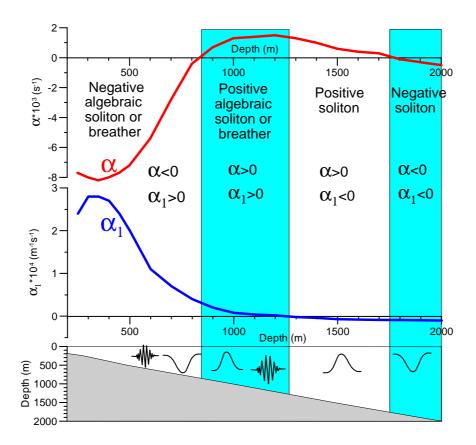


Figure 4: Quadratic  $\alpha$  and cubic  $\alpha_1$  coefficients of nonlinearity of the Gardner equation (2) as functions of depth.

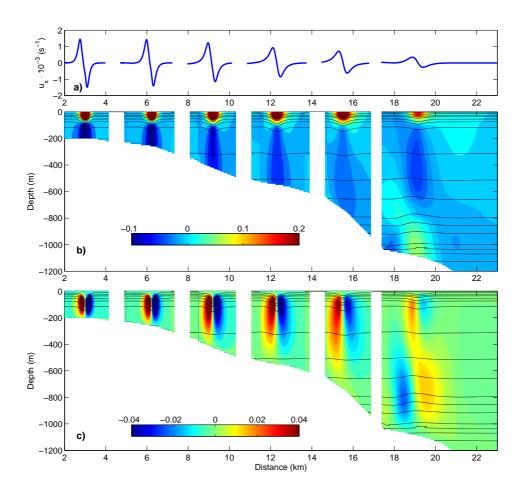


Figure 5: (a) Gradient of the horizontal velocity at the free surface  $\partial u/\partial x(z = 0)$ , (b) horizontal velocity overlaid with the temperature field and (c) vertical velocity overlaid with the temperature field of the ISW propagated seaward at different stages of its evolution. Colour bars show the velocity in  $ms^{-1}$ . Both panels are a composite of six different moments in time. Black solid lines depict isotherms.

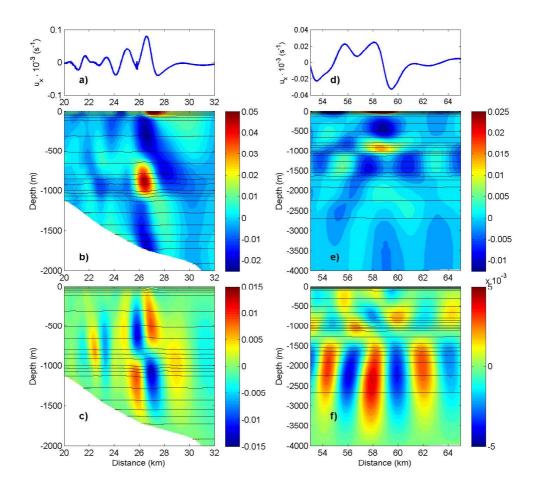


Figure 6: The same as Fig.5 but for the latest stages of ISW evolution.

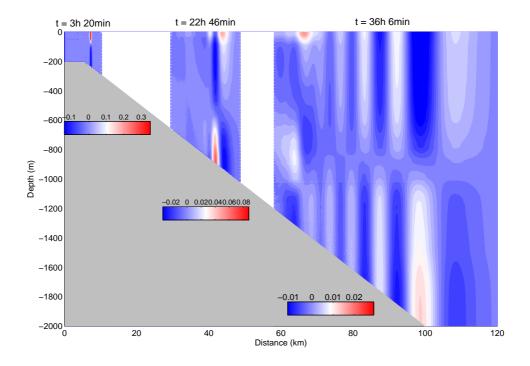


Figure 7: Horizontal velocity of the ISW propagated seaward over a gently sloping topography at three different stages of its evolution.

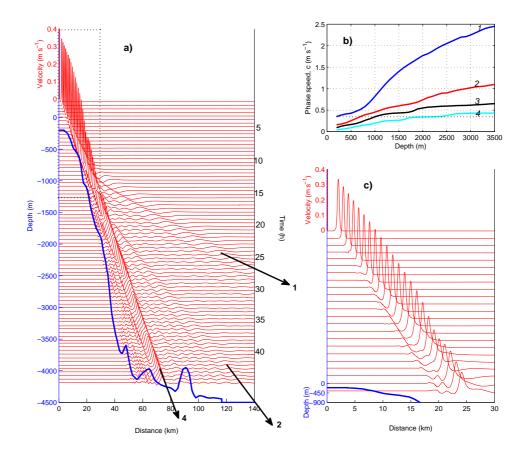


Figure 8: (a) Horizontal velocity produced at the free surface by a 53 m ISW propagated from 200 m deep shelf into the open sea. The time interval between two successive records is 2000 sec. The bottom profile is shown by a blue solid line. Arrows with numbers mark radiated wave packets of the corresponding mode. (b) Phase speed of four first modes calculated using the BVP (1) as a function of depth. (c) Zoom of the fragment depicted in panel (a) by a dashed rectangle.

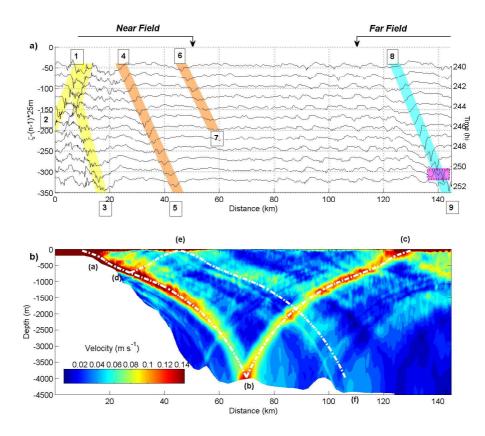


Figure 9: (a) Horizontal profiles of the isotherm  $13^{\circ}$ C taken with a 1 hour time interval after 20 tidal periods of model time. Vertical displacement  $\zeta$  of the isotherm from its equilibrium depth of 47 m is calculated using the formula depicted on the vertical axis. Numbers n = 1, 2, ..., 12 are counted from the topmost curve. (b) Amplitude of horizontal velocity calculated for the time span 240-252 h. The Levitus based buoyancy frequency profile (see Fig.2 a) was used in this run.

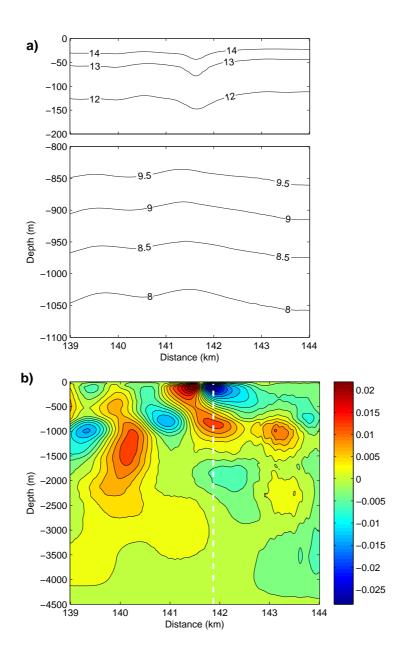


Figure 10: (a) Isotherms and (b) and vertical velocity field of the fragment depicted in Fig.9 a by a magenta rectangle.

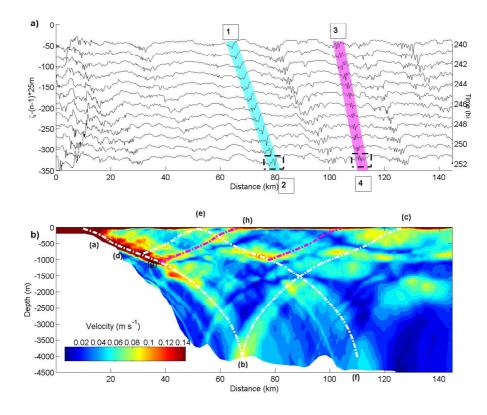


Figure 11: The same as in Fig.9 but for the original buoyancy frequency profile (the thin line in Fig.2 a). Two extra wave systems, (1)-(2) and (3)-(4), are not visible in Fig.9.

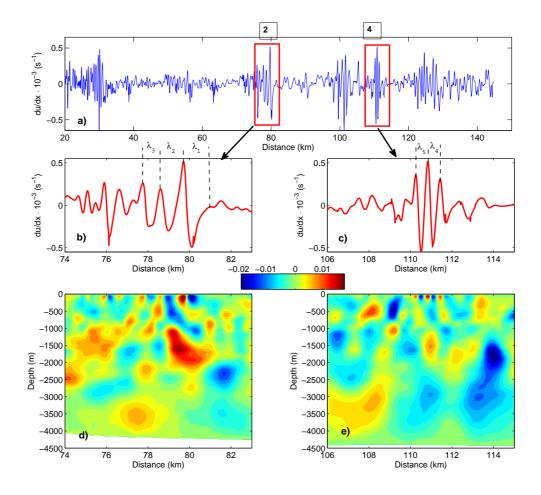


Figure 12: (a) Gradient of the horizontal velocity at the free surface  $\partial u/\partial x(z=0)$  after 252 hours of the model run (see bottom line in Fig.11 a). Wave systems (1)-(2) and (3)-(4) in Fig.11 are marked here by red rectangles with numbers 2 and 4, respectively. (b) and (c) Zoom of two fragments shown in panel (a) by red rectangles. (d) and (f) Vertical velocity of the two wave fragments shown in panels (b) and (c).

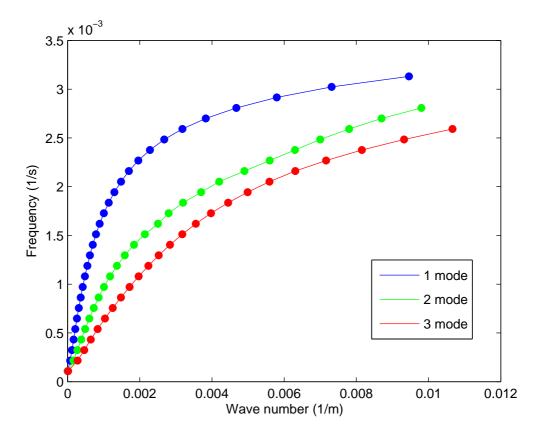


Figure 13: The dispersion relations calculated using the BVP (7) for the first (blue), second (green), and third (red) baroclinic modes.

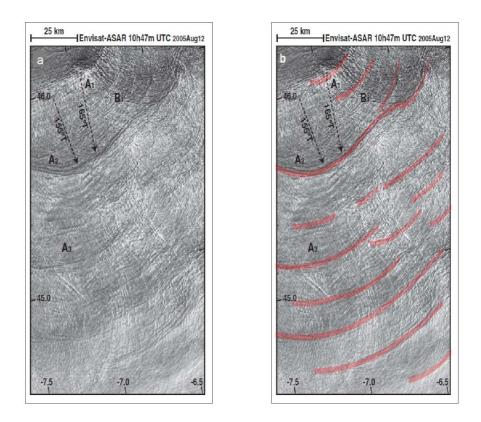


Figure 14: a) Envisat-ASAR image acquired on 12 August 2005 at 10 h 47 m UTC (Muacho et al., 2014). b) The same image with marked by red signatures of ISW packets.